

COMPUTER SIMULATION OF PANTOGRAPH DELAY DIFFERENTIAL EQUATIONS

by

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Ritz method is widely used in variational theory to search for an approximate solution. This paper suggests a Ritz-like method for integral equations with an emphasis of pantograph delay equations. The unknown parameters involved in the trial solution can be determined by balancing the fundamental terms.

*Key words: integral equation, series solution, variational principle,
Pantograph delay differential equation*

Introduction

The Ritz method or the Rayleigh-Ritz method is a famous analytical technology in the variational theory [1]. The application of the method requires establishment of a variational formulation for the discussed problem, which might be more complex than the solution process for a non-linear problem. The semi-inverse method [2-8] is a widely used to build up a needed variational principle, a trial solution with some unknown parameters is chosen and the unknowns can be identified by the stationary condition of the variational functional. In this paper we show that the idea can be extended to solving integral equations, and the unknowns in the trial solution can be approximately determined:

$$y''(x) = f[y(x), x] + g[y(x - \tau)] + \sum_{i=1}^n y(\sigma_i x), \quad y(0) = \alpha, \quad y'(0) = \beta \quad (1)$$

where τ , σ_i , α , and β are the constants, f and g – the functions.

Equations (1) can be solved by various methods, *e. g.*, the Taylor series method [9-13], the variational iteration method [14-19] and the homotopy perturbation method [20-27].

Ritz-like method

Similar to the Ritz method, we can assume that the solution has the form:

$$y(x) = \sum_{n=0}^N a_n x^n \quad (2)$$

where a_n ($n = 0 \sim N$) are unknown constants.

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Submitting eq. (2), combining the like terms of x^n , and setting the coefficients of x^n ($n = 0 \sim N - 2$) to zero, we obtain algebraic equations for a_n ($n = 0 \sim N$) by taking into account the initial conditions $y(0) = \alpha$, $y'(0) = \beta$.

Alternatively, we can assume the solution has the form:

$$y(x) = \frac{\sum_{n=0}^N B_n(x)}{\sum_{m=0}^M A_m(x)} \quad (3)$$

where $A_m(x)$ ($m = 0 \sim M$) and $B_n(x)$ ($n = 0 \sim N$) are basis functions. If we choose $A_m(x) = a_m x^m$ and $B_n(x) = b_n x^n$, the trial solution has the form:

$$y(x) = \frac{\sum_{n=0}^N b_n x^n}{\sum_{m=0}^M a_m x^m} \quad (4)$$

Example 1

We consider the following multi-pantograph delay equation [28]:

$$y'(x) = -\frac{5}{6}y(x) + 4y\left(\frac{1}{2}x\right) + 9y\left(\frac{1}{3}x\right) + x^2 - 1, \quad y(0) = 1, \quad 0 < x \leq 1 \quad (5)$$

We assume that the solution has the form:

$$y(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3 \quad (6)$$

Submitting eq. (6) into eq. (5):

$$\begin{aligned} a_1 + 2a_2 x + 3a_3 x^2 = & -\frac{5}{6}(a_0 + a_1 x + a_2 x^2 + a_3 x^3) + 4\left(a_0 + \frac{1}{2}a_1 x + \frac{1}{4}a_2 x^2 + \frac{1}{8}a_3 x^3\right) + \\ & + 9\left(a_0 + \frac{1}{3}a_1 x + \frac{1}{9}a_2 x^2 + \frac{1}{27}a_3 x^3\right) + x^2 - 1 \end{aligned} \quad (7)$$

It is easy to obtain the following algebra equations:

$$a_1 = -\frac{5}{6}a_0 + 4a_0 + 9a_0 - 1 \quad (8)$$

$$2a_2 = -\frac{5}{6}a_1 + 2a_1 + 3a_1 \quad (9)$$

$$3a_3 = -\frac{5}{6}a_2 + a_2 + a_2 + 1 \quad (10)$$

$$3a_3 = -\frac{5}{6}a_3 + \frac{1}{2}a_3 + \frac{1}{3}a_3 \quad (11)$$

Solving the aforementioned algebra system:

$$a_0 = 1 \quad (12)$$

$$a_1 = \frac{67}{6} \quad (13)$$

$$a_2 = \frac{1675}{72} \quad (14)$$

$$a_3 = \frac{12157}{1296} \quad (15)$$

Therefore we obtain the approximate solution:

$$y(x) = 1 + \frac{67}{6}x + \frac{1675}{72}x^2 + \frac{12157}{1296}x^3 \quad (16)$$

which happens to be the exact one.

Example 2

Consider the following delay equation [28]:

$$y''(x) = \frac{3}{4}y(x) + y\left(\frac{1}{2}x\right) - \frac{\frac{3}{4}}{1+x+x^2} - \frac{4}{4+2x+x^2} + \frac{2(1+2x)^2}{(1+x+x^2)^3} - \frac{2}{(1+x+x^2)^2} \quad (17)$$

with the following initial conditions:

$$y(0) = 1, \quad y'(0) = -1 \quad (18)$$

We assume the solution has the form:

$$y(x) = \frac{b_0}{a_0 + a_1x + a_2x^2 + a_3x^3} \quad (19)$$

By a similar solution process as that of *Example 1*, the unknown parameters in eq. (19) can be identified:

$$y(x) = \frac{1}{1+x+x^2+x^3} \quad (20)$$

which is the exact solution.

Discussion and conclusion

The present method can be easily extended to the case with fractal derivatives [29, 30]:

$$\frac{d^2y}{dx^{2\eta}} = f[y(x), x] + g[y(x-\tau)] + \sum_{i=1}^n y(\sigma_i x), \quad y(0) = \alpha, \quad \frac{dy}{dx^\eta}(0) = \beta \quad (21)$$

By the two-scale transform [7]:

$$X = x^\eta \quad (22)$$

Equation (21) is converted:

$$\frac{d^2y}{dX^2} = f[y(x), x] + g[y(x-\tau)] + \sum_{i=1}^n y(\sigma_i x), \quad y(0) = \alpha, \quad \frac{dy}{dX}(0) = \beta \quad (23)$$

The solution process for eq. (23) is previously illustrated, so it is easy to solve fractal differential equations.

The non-linear equations with delay terms are difficult to be solved, this paper proposes a simple but effective method for such problems. The results strongly depend upon the initial solution, a suitable choice of the initial solution will always lead to a good result.

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