

## OLDROYD-B NANOFUID-FLOW BETWEEN STRETCHING DISKS WITH THERMAL SLIP AND MULTIPLE FLOW FEATURES

by

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*This novel investigation deals with the thermal slip in magnetized axi-symmetric flow of Oldroyd-B liquid configured by infinite stretchable disks. With appliance of fundamental laws, the flow model equations are constructed. The governing flow equations are altered into no-dimensional form by using similarity quantities. The solution procedure is followed by using famous homotopy analysis technique. The convergence analysis is performed to evaluate the solution accuracy. The significance of flow parameters in the pattern of velocity, temperature and concentration are graphically illustrated. The novel numerical simulations for wall shear stress, Nusselt number, and Sherwood number are also performed at both surfaces of disks. It is noted the effects of relaxation time and retardation constants on radial and normal velocity components is opposite. The thermal slip parameters enhance the nanoparticles temperature. The concentration profile is decreases with Brownian motion parameter.*

Key words: *Oldroyd-B fluid, stretching disks, slip flow, magnetic field, homotopy analysis method*

### Introduction

Recently, the dynamic interest of researchers is developed towards the flow simulations induced by stretchable disks which include the applications of semi-conductors, rotating wafers, suction flow modelling, viscometer, diffusers, geothermal engineering, thrust bearings, biomechanics, power transmission, etc. The micro-devices structured on the disks applications allow various types of fundamental applications in biomedical, surgical apparatus, micro-channels, motors, pumps, electronic cooling, etc. The fundamental investigation on flow induced by stretchable disks was pioneered by Karman [1] which provides a direction many investigators to work on this topic. Many investigators studied the disk flow phenomenon under various flow conditions and diverse flow features. For instance, Hayat *et al.* [2]

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utilized the modified heat and mass flux expressions to explore the heat transfer phenomenon for third grade liquid configured by stretching disks. The stagnation point analysis for hydro-magnetic-flow between stretching disks was numerically focused by Turkyilmazoglu [3]. In another investigation, Turkyilmazoglu [4] examined the features of heat transfer in asymmetric flow of viscous material induced by shrinking and rotating disk. The magnetic field features for viscous fluid-flow between convectively heated disks was worked out by Soid *et al.* [5]. The utilization of nanoparticles in Newtonian fluid for uniformly moving disks was intended by Yin *et al.* [6]. Some interesting numerical simulations for flow problem induced by stretchable disks has been focused by Turkyilmazoglu [7]. The mixed convection impact for flow of Oldroyd-B material in isothermal moving disks was analyzed by Hashmi *et al.* [8]. Rashidi *et al.* [9] examined the slip features while examining the diffusion-thermo aspects in stretching disks. Khan *et al.* [10] find out the analytical solution for disk flow of viscous fluid by following convergent procedure. In another analysis, Khan *et al.* [11] reported the joule heating and viscous dissipation aspects in axi-symmetric flow encountered by stretching disks.

The investigation regarding the flow of non-Newtonian materials is another attracting research area in recent century due to their novel industrial, engineering and daily life applications. The non-Newtonian fluid possessed non-linear interaction shear stress and warping change. The prime reason behind such motivating attention of researchers towards the non-Newtonian fluid is justified due to their prestigious applications in the chemical industries, engineering processes, medical applications, food industries, mechanical sciences, processing industries and many more. The complicated rheological consequences of such materials insisted the scientists to suggest unique relationship for each non-Newtonian fluid model. Among various proposed fluid models, Oldroyd-B fluid one the most interesting and useful non-linear model which successfully allow to examine the important relaxation and retardation features. This model is characterized to the rate type fluids and presents the results for Maxwell fluid and viscous material as a limiting case. Owing to these valuable properties of Oldroyd-B fluid, many researchers used this model under different circumstances. For instance, Zheng *et al.* [12] reported the hydromagnetic-flow of Oldroyd-B liquid over an accelerating surface. The stretched flow of Oldroyd-B fluid has been reported by Hayat *et al.* [13]. They adopted convergence algorithm to communicate the solution procedure. The modelling for fractional type of Oldroyd-B under the impact of slip was led by Zheng *et al.* [14]. The flow Oldroyd-B fluid under the creeping constraints with applications of DLM simulations has been notified by Chiu *et al.* [15]. Farooq *et al.* [16] thrashed out the major consequences of Oldroyd-B fluid analytically.

The fluid-flow under the influence of magnetic force reports many narrative applications and studied by many investigators in recent years. The implications of magnetic field for such liquids flow provide us to avert the uncertain deviations of viscosity lubrications with temperature in the operational conditions of extreme type. The MHD has key applications in physics, chemistry, engineering and mathematics such as cancer therapy, strips cooling, power generation, drug delivery, nuclear plants, safer surgery, sample mixing, tumor elimination, MHD pumps gastric medication, sterilized devices, biological transportation, *etc.* Some recent investigations for various fluid-flow under the impact of magnetic field can be seen in references [17-24].

After carefully evaluating the aforementioned literature survey, aim here to report the heat and mass transportation for flow of Oldroyd-B nanofluid confined by stretching and rotating disks. The Brownian motion and thermophoresis aspects are taken into consideration. The flow is subjected to the magnetic force. The thermal slip features are utilizes to explore the thermal performances of non-Newtonian fluid. It is remarked that some studies are already

available in the literature regarding flow due to stretching disks but velocity and thermal slip features in flow of Oldroyd-B nanofluid is not reported yet. In order to fill this research gap, present communication is reported. The governing equations are modeled and then retained dimensional forms. The analytical solution is computed with appliance of homotopy analysis scheme [25-30]. The solution convergence is also examined. The flow parameters for velocity, temperature and concentration are discussed with physical applications.

**Mathematical modelling**

Let us develop a nanofluid model for Oldroyd-fluid by utilizing the thermal slip features. The non-Newtonian fluid is confined between stretchable disks where flow is imagined to be 2-D. At the surfaces of disks, the velocity and thermal slip constraints are elaborated. The magnetic force consequences has been reported along-axis. The temperature at lower surface of disk is while is upper surface temperature. The famous cylindrical axes and are followed to model the problem. Due to the axisymmetry constraints, the physical quantities are free of The equations for Oldroyd-B liquid with impact of magnetic force, nanoparticles and thermophoresis features are expressed [8]:

$$\frac{1}{r} \frac{\partial}{\partial r}(ru) + \frac{\partial w}{\partial z} = 0 \tag{1}$$

$$\begin{aligned} u \frac{\partial u}{\partial r} + w \frac{\partial u}{\partial z} = & -\frac{1}{\rho} \frac{\partial p}{\partial r} + \nu \left( 2 \frac{\partial^2 u}{\partial r^2} + \frac{\partial^2 w}{\partial r \partial z} + \frac{\partial^2 u}{\partial z^2} + \frac{2}{r} \frac{\partial u}{\partial r} - 2 \frac{u}{r^2} \right) - \\ & -\beta_1^* \left( w^2 \frac{\partial^2 u}{\partial z^2} + 2uw \frac{\partial^2 u}{\partial r \partial z} + \frac{\partial^2 u}{\partial r^2} \right) + \nu \beta_2^* \left[ \frac{4u^2}{r^3} - \frac{2w}{r^2} \frac{\partial u}{\partial z} - \frac{1}{r} \left( \frac{\partial u}{\partial z} \right)^2 - \right. \\ & -2 \frac{\partial u}{\partial z} \frac{\partial^2 w}{\partial z^2} + w \frac{\partial^3 u}{\partial z^3} - \frac{2u}{r^2} \frac{\partial u}{\partial r} - \frac{\partial^2 u}{\partial z^2} \frac{\partial u}{\partial r} - \frac{2}{r} \left( \frac{\partial u}{\partial r} \right)^2 - \frac{1}{r} \frac{\partial u}{\partial z} \frac{\partial w}{\partial r} + \frac{2w}{r} \frac{\partial^2 u}{\partial r \partial z} - \\ & - \frac{\partial u}{\partial z} \frac{\partial^2 u}{\partial r \partial z} - \frac{\partial u}{\partial r} \frac{\partial^2 w}{\partial r \partial z} + u \frac{\partial^3 u}{\partial r \partial z^2} + w \frac{\partial^3 w}{\partial r \partial z^2} + \frac{2u}{r} \frac{\partial^2 u}{\partial r^2} - 2 \frac{\partial u}{\partial r} \frac{\partial^2 u}{\partial r^2} - \\ & \left. - \frac{\partial u}{\partial z} \frac{\partial^2 w}{\partial r^2} + 2w \frac{\partial^3 u}{\partial r^2 \partial z} + u \frac{\partial^3 w}{\partial r^2 \partial z} + 2u \frac{\partial^3 u}{\partial r^3} \right] + \frac{\sigma B_0^2}{\rho} \left( -u - \beta_1^* w \frac{\partial u}{\partial z} \right) \end{aligned} \tag{2}$$

$$\begin{aligned} u \frac{\partial w}{\partial r} + w \frac{\partial w}{\partial z} = & -\frac{1}{\rho} \frac{\partial p}{\partial z} + \nu \left( \frac{\partial^2 w}{\partial r^2} + \frac{\partial^2 u}{\partial r \partial z} + 2 \frac{\partial^2 w}{\partial z^2} + \frac{1}{r} \frac{\partial w}{\partial r} + \frac{1}{r} \frac{\partial u}{\partial r} \right) - \\ & -\beta_1^* \left( w^2 \frac{\partial^2 u}{\partial z^2} + 2uw \frac{\partial^2 u}{\partial r \partial z} + u^2 \frac{\partial^2 u}{\partial r^2} \right) + \nu \beta_2^* \left( -\frac{u}{r^2} \frac{\partial u}{\partial z} - \frac{1}{r} \frac{\partial u}{\partial z} \frac{\partial w}{\partial z} + \frac{w}{r} \frac{\partial^2 u}{\partial z^2} - \right. \\ & -2 \frac{\partial w}{\partial z} \frac{\partial^2 w}{\partial z^2} + 2w \frac{\partial^3 w}{\partial z^3} + \frac{u}{r^2} \frac{\partial w}{\partial r} - \frac{1}{r} \frac{\partial w}{\partial r} \frac{\partial w}{\partial z} - \frac{\partial^2 u}{\partial z^2} \frac{\partial w}{\partial r} - \frac{2}{r} \frac{\partial u}{\partial r} \frac{\partial w}{\partial r} + \frac{u}{r} \frac{\partial^2 u}{\partial r \partial z} - \\ & - \frac{\partial w}{\partial z} \frac{\partial^2 u}{\partial r \partial z} + \frac{w}{r} \frac{\partial^2 w}{\partial r \partial z} - \frac{\partial w}{\partial r} \frac{\partial^2 w}{\partial r \partial z} + w \frac{\partial^3 u}{\partial r \partial z^2} + 2u \frac{\partial^3 w}{\partial r \partial z^2} \left. \right) - 2 \frac{\partial w}{\partial r} \frac{\partial^2 u}{\partial r^2} + \\ & + \frac{u}{r} \frac{\partial^2 w}{\partial r^2} - \frac{\partial w}{\partial z} \frac{\partial^2 w}{\partial r^2} + u \frac{\partial^3 u}{\partial r^2 \partial z} + w \frac{\partial^3 w}{\partial r^2 \partial z} + u \frac{\partial^3 w}{\partial r^3} \end{aligned} \tag{3}$$

$$u \frac{\partial T}{\partial r} + w \frac{\partial T}{\partial z} = \alpha \left( \frac{\partial^2 T}{\partial r^2} + \frac{1}{r} \frac{\partial T}{\partial r} + \frac{\partial^2 T}{\partial z^2} \right) + \tau \left[ D_B \left( \frac{\partial C}{\partial r} \frac{\partial T}{\partial r} + \frac{\partial C}{\partial z} \frac{\partial T}{\partial z} \right) + \frac{D_T}{T_m} \left\{ \left( \frac{\partial T}{\partial r} \right)^2 + \left( \frac{\partial T}{\partial z} \right)^2 \right\} \right] + Qk_0 a_0 e^{-E/R_1 T} \quad (4)$$

$$u \frac{\partial C}{\partial r} + w \frac{\partial C}{\partial z} = D_B \left( \frac{\partial^2 C}{\partial r^2} + \frac{1}{r} \frac{\partial C}{\partial r} + \frac{\partial^2 C}{\partial z^2} \right) + \frac{D_T}{T_m} \left( \frac{\partial^2 T}{\partial r^2} + \frac{1}{r} \frac{\partial T}{\partial r} + \frac{\partial^2 T}{\partial z^2} \right) - \frac{\partial [V_T (C - C_1)]}{\partial z} \quad (5)$$

The slip boundary conditions for formulated flow problem:

$$u = ar + \left( \frac{2 - \sigma_u}{\sigma_u} \right) \tau_1 \frac{\partial u}{\partial z} + \left( \frac{2 - \sigma_u}{\sigma_u} \right) \tau_1^2 \frac{\partial^2 u}{\partial z^2}, \quad w = 0, \quad p = \frac{a\mu\beta_1 r^2}{4d^2}, \quad \text{at } z = 0 \quad (6)$$

$$u = cr - \left( \frac{2 - \sigma_u}{\sigma_u} \right) \tau_1 \frac{\partial u}{\partial z} - \left( \frac{2 - \sigma_u}{\sigma_u} \right) \tau_1^2 \frac{\partial^2 u}{\partial z^2}, \quad w = 0, \quad p = 0, \quad \text{at } z = d$$

Similarly the boundary conditions for nanoparticles temperature are also imposed in form of following jump slip relations:

$$T = T_1 + \left( \frac{2 - \sigma_T}{\sigma_T} \right) \left( \frac{2\xi}{\xi + 1} \right) \frac{1}{\text{Pr}} \tau_2 \frac{\partial T}{\partial z} + \left( \frac{2 - \sigma_T}{\sigma_T} \right) \left( \frac{2\xi}{\xi + 1} \right) \frac{1}{\text{Pr}} \frac{\tau_2^2}{2} \frac{\partial^2 T}{\partial z^2}, \quad \text{at } z = 0 \quad (7)$$

$$T = T_2 - \left( \frac{2 - \sigma_T}{\sigma_T} \right) \left( \frac{2\xi}{\xi + 1} \right) \frac{1}{\text{Pr}} \tau_2 \frac{\partial T}{\partial z} + \left( \frac{2 - \sigma_T}{\sigma_T} \right) \left( \frac{2\xi}{\xi + 1} \right) \frac{1}{\text{Pr}} \frac{\tau_2^2}{2} \frac{\partial^2 T}{\partial z^2}, \quad \text{at } z = d \quad (8)$$

The nanoparticles concentration is reported by using following no-slip conditions:

$$C = C_1, \quad z = 0, \quad C = C_2 \quad \text{at } z = d \quad (9)$$

The physical quantities are radial component,  $u$ , axial component,  $w$ , pressure,  $p$ , fluid density,  $\rho$ , dynamic viscosity,  $\mu$ , kinematic viscosity,  $\nu$ , relaxation time,  $\beta_1^*$ , retardation time  $\beta_2^*$ , temperature,  $T$ , thermal diffusivity,  $K$ , concentration,  $C$ , thermophoretic coefficient,  $D_T$ , mean temperature,  $T_m$ , thermophoretic velocity,  $V_T$ , Brown diffusion coefficient,  $D_B$ , thermal accommodation coefficient,  $\sigma_T$ , specific heat ratio,  $\xi$ , stretching rates constants,  $a$  and  $b$ , tangential momentum accommodation constant,  $\sigma_u$ , and molecular mean path,  $\tau_1$ .

The dimensionless form of given equations can be resulted via relations [8]:

$$u = -\frac{ar}{2} H'(\eta), \quad w = adH(\eta), \quad p = a\mu \left[ P(\eta) + \frac{\beta_1 r^2}{4d^2} \right], \quad \eta = \frac{z}{d} \quad (10)$$

$$T = T_1 + (T_2 - T_1)\theta(\eta), \quad C = C_1 + (C_2 - C_1)\varphi(\eta)$$

After altering these relations, set of dimensionless equations is obtained:

$$\frac{\text{Re}}{2} (H'^2 - 2HH'') = - \left\{ \beta_1 + H''' + \lambda_1' a \text{Re} (HH'H'' - H^2 H''') + \lambda_2' a [HH^{(iv)} - H''^2] \right\} + \text{Re M} (H' + \lambda_1' a HH'') \quad (11)$$

$$\theta'' - \text{Re Pr} H \theta' + Nb \text{Pr} \theta' \varphi' + Ni \text{Pr} \varepsilon \theta'^2 + K \exp \left[ \frac{-1}{\varepsilon(1 + \varepsilon\theta)} \right] = 0 \quad (12)$$

$$\varphi'' - \text{Re} \text{LePr} H \varphi' + \left( \frac{Nt}{Nb} \right) \varepsilon \theta'' + \mathcal{J} \text{LePr} \varepsilon (\theta' \varphi' + \varphi \theta'') = 0 \quad (13)$$

$$P' = \frac{3H''}{2} - \text{Re} H H' - \lambda_1 \text{Re} H^2 H'' \quad (14)$$

$$H(0) = 0, H(1) = 0, H'(0) = -2 + [\varepsilon_1 H''(0) + \varepsilon_2 H'''(0)] \quad (15)$$

$$H'(1) = -2\gamma - [\varepsilon_1 H''(0) + \varepsilon_2 H'''(0)], P(0) = 0 \quad (16)$$

$$\theta(0) = \varepsilon_3 \theta'(0) + \varepsilon_4 \theta''(0), \theta(1) = 1 - [\varepsilon_3 \theta'(1) + \varepsilon_4 \theta''(1)] \quad (17)$$

$$\varphi(0) = 0, \varphi(1) = 1 \quad (18)$$

The dimension variables are Reynolds number, Re, Deborah number for relaxation,  $\lambda_1$ , retardation time,  $\lambda_2$ , wall stretching parameter,  $\gamma$ , first order velocity slip,  $\varepsilon_1$ , Hartmann number, M, Prandtl number, Pr, second order velocity slip parameter,  $\varepsilon_2$ , first order temperature jump parameter,  $\varepsilon_3$ , temperature jump parameter of second order,  $\varepsilon_4$ , Schmidt number, Sc, ratio of diffusion coefficient,  $\delta$ , and Knudsen number, Kn, which are defined:

$$\gamma = \frac{c}{a}, \lambda_1 = \beta_1^* a, \text{Re} = \frac{ad^2}{\nu}, \text{Pr} = \frac{\nu}{\alpha}, \text{Kn} = \frac{\tau_{1,2}}{d}$$

$$\lambda_2 = \beta_2^* a, \varepsilon_1 = \text{Kn} \left( \frac{2 - \sigma_u}{\sigma_u} \right), \varepsilon_2 = \frac{\text{Kn}^2}{2} \left( \frac{2 - \sigma_u}{\sigma_u} \right)$$

$$\varepsilon_3 = \text{Kn} \left( \frac{2 - \sigma_T}{\sigma_T} \right) \left( \frac{2\xi}{\xi + 1} \right) \frac{1}{\text{Pr}}, \varepsilon_4 = \frac{\text{Kn}^2}{2} \left( \frac{2 - \sigma_T}{\sigma_T} \right) \left( \frac{2\xi}{\xi + 1} \right) \frac{1}{\text{Pr}}, \delta = \frac{D_B}{D_A}$$

From eq. (17), the constant  $\beta_1$  is illuminated:

$$H^{(iv)} = \text{Re} H H'' - \lambda_1 \text{Re} [-H H' H'' - H^2 H^{(iv)} + H H'^2 + H'^2 H''] -$$

$$-M \text{Re} [H'' + \lambda_1 (H' H'' + H H''')] - \lambda_2 [-2H'' H''' + H' H^{(iv)} + H H^{(v)}] \quad (19)$$

Following mathematical expressions are notified to explore the numerical features of skin friction coefficient, Sherwood number and Nusselt number confined at both disks walls:

$$C_{1f,2f} = \frac{\tau_{rz}|_{\eta=0,1}}{\frac{1}{2} \rho (\delta r)^2} = 2 \text{Re}^{-1} H''(\eta)|_{\eta=0,1}, N_{1u,2u} = -\frac{dk_T \frac{\partial T}{\partial z}|_{\eta=0,1}}{k_T (T_2 - T_1)} = -\theta'(\eta)|_{\eta=0,1} \quad (20)$$

$$\text{Sh} = \frac{-\left( D \frac{\partial C}{\partial z} \right)|_{\eta=0,1}}{D(C_1 - C_2)} = -\varphi'(\eta)|_{\eta=0,1} \quad (21)$$

### Method of solution

The initial approximations in following forms are suggested to start the simulation procedure:

$$H_0(\eta) = \frac{1}{8\varepsilon_1 + 12\varepsilon_1^2} \left( -2\eta(1+\eta) \left\{ -1 + \eta(1+\gamma) + 2\varepsilon_1[-2 + \eta + \gamma(1+\eta)] - 6\varepsilon_2(1+\eta) \right\} \right) \quad (22)$$

$$\theta_0(\eta) = \frac{\eta + \varepsilon_3}{1 + 2\varepsilon_3}, \quad \varphi_0(\eta) = \eta \quad (23)$$

along with linear operators:

$$L_H = \frac{d^4}{d\eta^4}, \quad L_\theta = \frac{d^2}{d\eta^2}, \quad L_\varphi = \frac{d^2}{d\eta^2} \quad (24)$$

The approximations for zeroth- order are developed:

$$(1-q)L_H[H(\eta;q) - H_0(\eta)] = q\hbar_H N_H[H(\eta;q)] \quad (25)$$

$$(1-q)L_\theta[\theta(\eta;q) - \theta_0(\eta)] = q\hbar_\theta N_\theta[\theta(\eta;q)] \quad (26)$$

$$(1-q)L_\varphi[\varphi(\eta;q) - \varphi_0(\eta)] = q\hbar_\varphi N_\varphi[\varphi(\eta;q)] \quad (27)$$

The  $m^{\text{th}}$  order problem:

$$L_H[H_m(\eta) - \chi_m H_{m-1}(\eta)] = \hbar_H \text{Re}_{1m}(\eta) \quad (28)$$

$$L_\theta[\theta_m(\eta) - \chi_m \theta_{m-1}(\eta)] = \hbar_\theta \text{Re}_{2m}(\eta) \quad (29)$$

$$L_\varphi[\varphi_m(\eta) - \chi_m \varphi_{m-1}(\eta)] = \hbar_\varphi \text{Re}_{3m}(\eta) \quad (30)$$

$$H_m(0) = H_m(1) = 0, \quad H'_m(0) = [\varepsilon_1 H''_m(0) + \varepsilon_2 H'''_m(0)], \quad H'_m(1) = -[\varepsilon_1 H''_m(1) + \varepsilon_2 H'''_m(1)] \quad (31)$$

$$\theta_m(0) = [\varepsilon_3 \theta'_m(0) + \varepsilon_4 \theta''_m(0)], \quad \theta(1) = -[\varepsilon_3 \theta'_m(1) + \varepsilon_4 \theta''_m(1)] \quad (32)$$

$$\varphi_m(0) = 0, \quad \varphi_m(1) = 1 \quad (33)$$

$$\chi_m = \begin{cases} 0, & m \leq 1 \\ 1, & m > 0 \end{cases} \quad (34)$$

The computation software MATHEMATICA help out to facilitate the simulation procedure.

### Convergence of solution

After obtaining the analytical expressions successfully, aim of this section report the convergent analysis which has key importance in adopted convergent technique. The auxiliary parameters ( $\hbar_H, \hbar_\theta, \hbar_\varphi$ ) are play a diligent contribu-

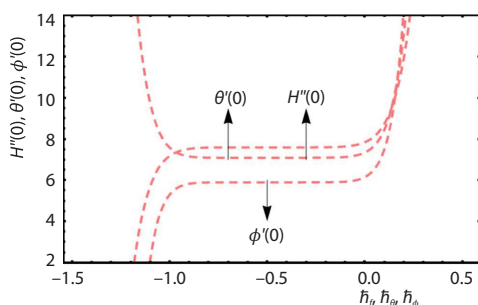


Figure 1. The  $\hbar$ -curves for velocity temperature and concentration profiles

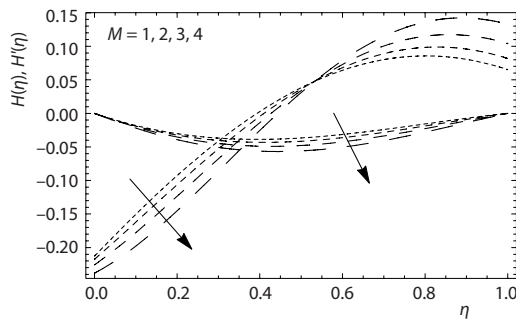
tion suggest the convergence procedure. The necessary  $\hbar$ -curves are constructed for velocity, temperature and concentration distributions are prepared under the specific values of parameters. The guaranteed convergence region is result under set of flow parameters. Figure 1 reports such convergence values which reveal that best convergence solution is associated with domain  $-1 \leq \hbar_H \leq -0.1$ ,  $-1.3 \leq \hbar_\theta \leq -0.2$ , and  $-1.2 \leq \hbar_\phi \leq -0.1$ . The convergence analysis for  $H''(0)$ ,  $\theta''(0)$ ,  $\phi''(0)$  is worked out in tab. 1 which shows that convergence of numerical values is achieved at 13<sup>th</sup> order of approximations.

**Table 1. The HAM convergence at different order of approximations**

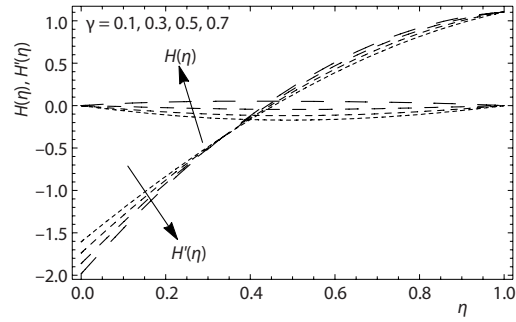
Approximation	$H''(0)$	$\theta''(0)$	$\phi''(0)$
5	6.66130	0.446623	0.243144
10	6.66121	0.446434	0.242136
12	6.65118	0.446334	0.242128
15	6.65110	0.446200	0.242120
20	6.65110	0.446200	0.242120

**Discussion**

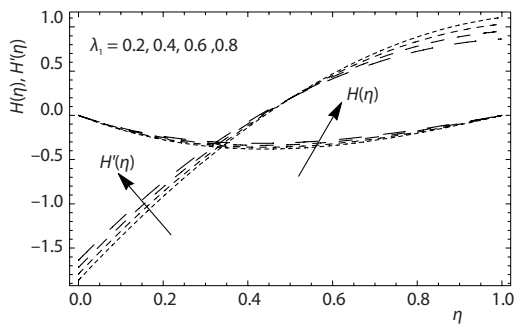
The physical consequences for a model flow problem are quite necessary to see the clear insight flow problem [31-34]. Now the physical aspects of flow problem against parameters are studied in this section. The graphical simulations are prepared in view of flow constraints parameters against velocity, temperature, and concentration which are already altered in dimensionless forms. The whole analysis is performed by keeping fixed values like  $Re = 0.5$ ,



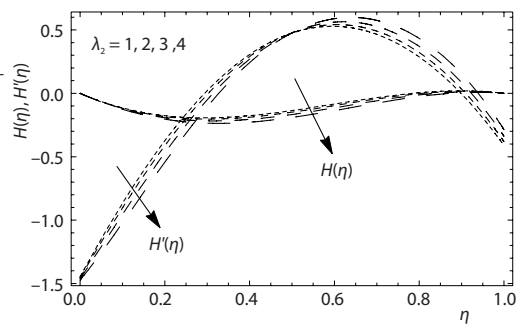
**Figure 2. Velocity components for M**



**Figure 3. Velocity components for  $\gamma$**



**Figure 4. Velocity components for  $\lambda_1$**



**Figure 5. Velocity components for  $\lambda_2$**

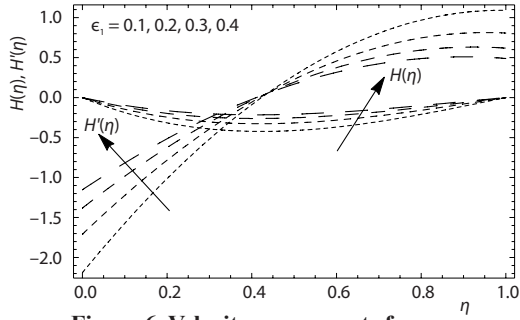


Figure 6. Velocity components for  $\varepsilon_1$

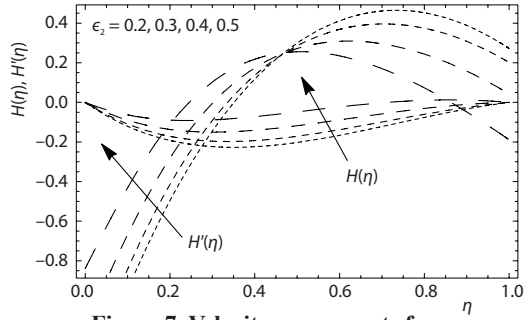


Figure 7. Velocity components for  $\varepsilon_2$

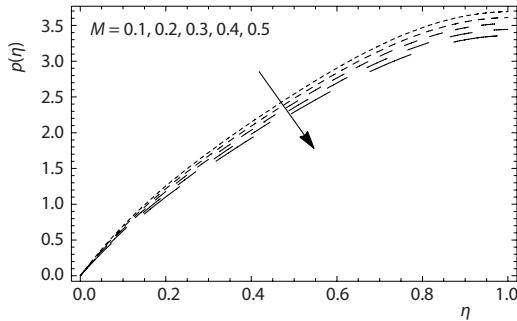


Figure 8. Change in pressure with  $M$

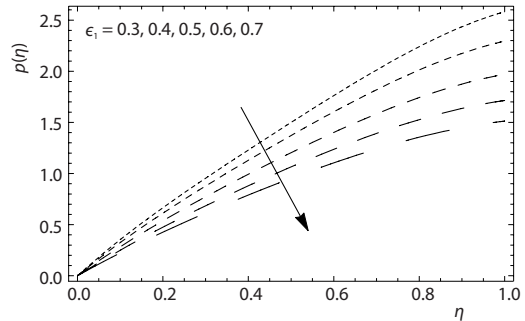


Figure 9. Change in pressure with  $\varepsilon_1$

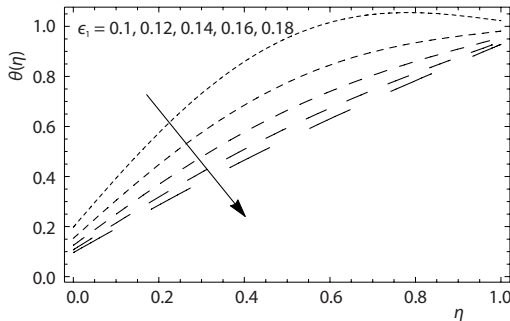


Figure 10. Change in temperature with  $\varepsilon_1$

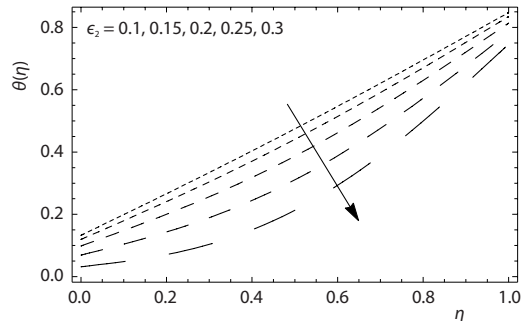


Figure 11. Change in temperature with  $\varepsilon_2$

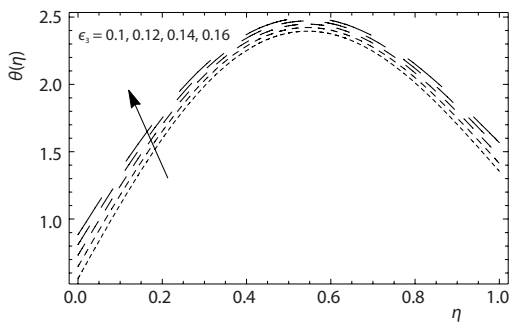


Figure 12. Change in temperature with  $\varepsilon_3$

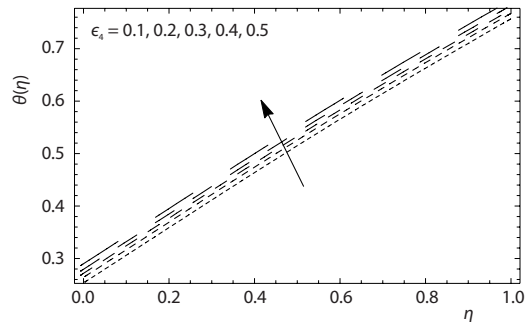


Figure 13. Change in temperature with  $\varepsilon_4$



$\gamma = 0.2$ ,  $M = 0.5$ ,  $Nb = 0.2$ ,  $Pr = 0.1$ ,  $\lambda_1 = 0.2$ ,  $\lambda_2 = 0.1$ ,  $\varepsilon_1 = 0.2$ ,  $\varepsilon_2 = 0.3$ ,  $\varepsilon_3 = 0.3$ , and  $\varepsilon_4 = 0.5$ . Figure 2 communicates the influence Hartmann number on radial and vertical velocity components. Due to resistance of Lorentz force associated with larger magnetic field result a decrement in velocity components up to a specific level. The plot for wall stretching constant,  $\gamma$ , against the radial and vertical velocities is prepared in fig. 3. Here a rise in both components notified with larger  $\gamma$  variation. The curve for relaxation constant,  $\lambda_1$ , and retardation constant,  $\lambda_2$ , are plotted in figs. 4 and 5, respectively. An improve velocity distributions is associated with  $\lambda_1$  in contrast to  $\lambda_2$ . Physically, with increment of relaxation time parameter, more time needed to retain the fluid original position. A lower distribution of radial and vertical components are noticed when  $\lambda_2$  is maximum. In fig. 6, the output of fist order velocity slip constant  $\varepsilon_1$  is suggested for velocity components. Both components increases when  $\varepsilon_1$  is larger varies. The opposite observations are specified for  $\varepsilon_2$  and examined by plotting fig. 7. Figures 8 and 9 report the change in pressure distribution for Hartmann number and  $\varepsilon_1$ , respectively. With larger assigns values to both Hartmann number and  $\varepsilon_1$ , the pressure distribution declined. However, the change in pressure is comparatively dominant for slip constant  $\varepsilon_1$ . Figures 10 and 11 give the temperature distribution,  $\theta$ , for velocity slip parameters  $\varepsilon_1$  and  $\varepsilon_2$ . The observations claim a lower temperature profile with both parameters. The change in  $\theta$  due to thermal slip parameters  $\varepsilon_3$  and  $\varepsilon_4$  is reported

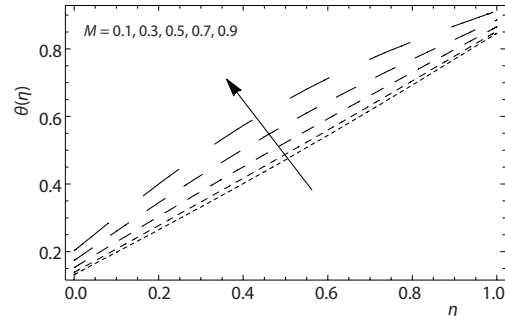


Figure 14. Change in temperature with M

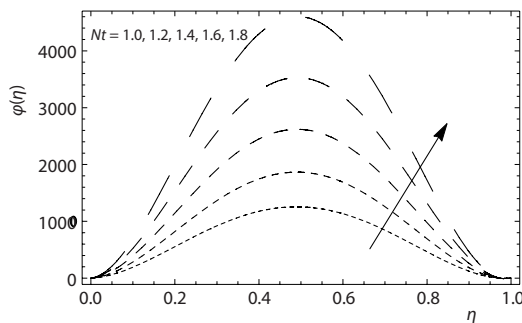


Figure 15. Change in concentration with Nt

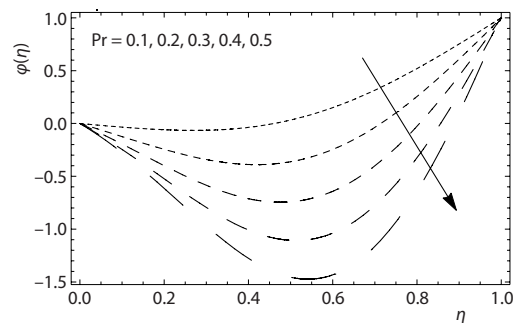


Figure 16. Change in concentration with Pr

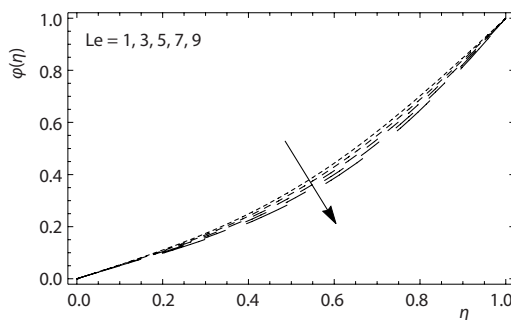


Figure 17. Change in concentration with Le

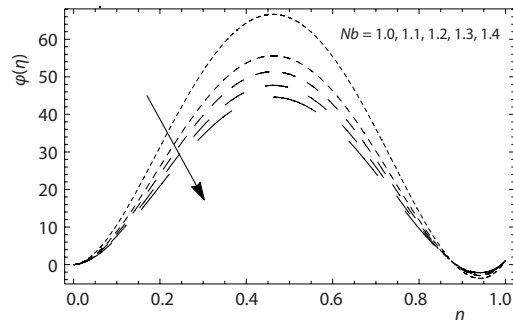


Figure 18. Change in concentration with Nb

by preparing figs. 12 and 13. Here, an increasing trend is noted for  $\theta$  for both constants. Therefore, it is remarked that consideration of thermal slip features are more effective to improve the heat transportation processes. The graphical results for Hartmann number are reported in fig. 14. The nanoparticles temperature is increasing when Hartmann number is maximum. Physically larger values of Hartmann number are associated with Lorentz force which increase the temperature. The results utilizes figs. 15-18 determine the change in nanoparticles concentration,  $\phi$ , with numerous values of thermophoresis parameter,  $Nt$ , Prandtl number, Lewis number, and Brownian motion constant,  $Nb$ . From fig. 15, upshot concentration distribution is observed when  $Nt$  is maximum. Physically, thermophoresis phenomenon represents the migration pattern of heated fluid particles towards the cold region. Due to this, temperature increases. The results reported in fig. 16 claim that concentration reduces with upshot values of Prandtl number. Figure 17 aim to presents the novel impact of Lewis number on  $\phi$ . Here the results claim a reduce nanoparticles concentration for Lewis number. Physically the Lewis number is inversely related to mass diffusivity due to higher Lewis number. Figure 18 presents the influence of  $Nb$  on  $\phi$ . As expected, concentration is lower for  $Nb$ .

The numerical expression based on the Nusselt number is evaluated in tab. 2. At lower disk surface, the heat transfer is minimum for Hartmann number. However, the upper wall show an increasing variation. The Nusselt number decreases for velocity slip parameter.

**Table 2. The variation of Nusselt number with different parameters**

$\varepsilon_1$	$\varepsilon_2$	$\varepsilon_3$	$\varepsilon_4$	Pr	M	Lower disk	Upper disk
0.2	0.5	0.5	0.2	1.0	0.3	-0.62653	-0.72854
0.4	0.5	0.5	0.2	1.0	0.3	-0.60435	-0.71095
0.6	0.5	0.5	0.2	1.0	0.3	-0.54675	-0.70462
0.2	0.1	0.5	0.2	1.0	0.3	-0.64478	-0.70741
0.2	0.3	0.5	0.2	1.0	0.3	-0.55535	-0.63751
0.2	0.6	0.5	0.2	1.0	0.3	-0.37754	-0.45679
	0.5	0.1	0.2	1.0	0.3	-0.60753	-0.63975
	0.5	0.3	0.2	1.0	0.3	-0.69278	-0.70568
	0.5	0.6	0.2	1.0	0.3	0.80549	-0.80653
	0.5	0.5	0.5	1.0	0.3	-0.54546	-0.44705
	0.5	0.5	1.0	1.0	0.3	-0.54587	-0.44764
	0.5	0.5	2.0	1.0	0.3	-0.54546	-0.44654
	0.5	0.5	0.2	0.2	0.3	-0.47742	-0.52534
	0.5	0.5	0.2	0.4	0.3	-0.47667	-0.52364
	0.5	0.5	0.2	0.6	0.3	-0.47522	-0.52457
	0.5	0.5	0.2	1.0	0.3	-0.47653	-0.54575
	0.5	0.5	0.2	1.0	0.5	-0.48984	-0.52653
	0.5	0.5	0.2	1.0	0.7	-0.49458	-0.50905

## Conclusions

The rheological consequences for Oldroyd-B nanofluid is studies in presence of velocity and thermal slip features. The modeled flow problem is analytically tackled via homotopy analysis method. The convergence procedure is followed to confirm the solution. The main results are as follows.

- The stretching ratio constant increases the radial and normal velocity components.
- An increment in radial and normal velocity components are noted for velocity slip parameters.

- The Hartmann number effectively controls the fluid particles movement at both surfaces of disks.
- A declining temperature distribution is observed for velocity slip parameters.
- The nanoparticles temperature can be enhanced with proper utilization thermal slip constants.
- The concentration profile is lower for Brownian motion constant, Lewis number and Prandtl number.
- The thermophoresis constant improve the nanoparticles concentration effectively.

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