

ON TRAVELING-WAVE SOLUTIONS FOR THE SCALING-LAW TELEGRAPH EQUATIONS

by

Xiao-Jun YANG^{a,b,c*}

^a State Key Laboratory for Geo-Mechanics and Deep Underground Engineering,
China University of Mining and Technology, Xuzhou, China

^b School of Mechanics and Civil Engineering, China University of Mining and Technology,
Xuzhou, China

^c College of Mathematics, China University of Mining and Technology, Xuzhou, China

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The aim of the study is to address the scaling-law telegraph equations with the Mandelbrot-scaling-law derivative. The traveling-wave solutions with use of the Kohlrausch-Williams-Watts function are considered in detail. The works are proposed to describe the physical models in complex topology.

Key words: *scaling-law telegraph equation, Leibniz derivative,
Mandelbrot-scaling-law derivative, traveling-wave solution,
Kohlrausch-Williams-Watts function*

Introduction

The telegraph equations, which are the original tasks proposed by Heaviside in 1876 [1], have been developed to describe the transmission line models with the classical derivative operator [2], which leads the diffusion problem. The mathematical models for the fractional telegraph equations based on the Riemann-Liouville sense [3] leads to the power-law behaviors of the Brownian time [4], and contacted the fractional diffusion process in [5].

The calculus with respect to monotone function (so-called the general calculus) goes back to many mathematicians, *e. g.*, Leibniz and Stieltjes [6-10]. The Leibniz derivative (so-called the derivative with respect to monotone function) was proposed by Leibniz in 1676 [11]. Based on the Riemann's work [12], the Stieltjes-Riemann integral (so-called the integral with respect to monotone function) was proposed by Stieltjes in 1894 [13]. The scaling-law derivative (so-called the derivative with respect to scaling-law function) was proposed in [7] and further reported in [9]. The scaling-law integral (so-called the integral with respect to scaling-law function) was proposed in [9]. Their geometric interpretations and the topology calculus were discussed in [6, 9].

The scaling theory can be applied to the complex circuit, which is experimentally confirmed in [14,15]. Considering the Brownian time and Mandelbrot-scaling-law behaviors [16] in the circuit, the aim of the paper is to derive the electrical phenomena, which involve the Leibniz derivative and Mandelbrot-scaling-law derivative, to propose the scaling-law telegraph equations and to present the traveling wave solutions via Kohlrausch-Williams-Watts function [17, 18].

The Leibniz derivative, Stieltjes integral and scaling-law calculus

The general calculus

Let $\psi_h(t) = (\psi \circ h)(t) = \psi[h(t)]$, where $h^{(1)}(t) > 0$, and let \mathbb{N} be the set of the integer numbers.

The Leibniz derivative of the function $\psi_h(t)$ is defined [6, 11]:

$$D_{t,h(\cdot)}^{(1)}\psi_h(t) = \frac{1}{h^{(1)}(t)} \frac{d\psi_h(t)}{dt} \quad (1)$$

The Leibniz derivative of high-order is defined [6, 11]:

$$D_{t,h(\cdot)}^{(n)}\psi_h(t) = \left[\frac{1}{h^{(1)}(t)} \frac{d}{dt} \right]^n \psi_h(t) \quad (2)$$

where $n \in \mathbb{N}$.

The Riemann-Stieltjes integral of the function $\psi_h(t)$ is defined:

$${}_a I_{b,h(\cdot)}^{(1)}\psi_h(t) = \int_a^b \psi_h(t) h^{(1)}(t) dt \quad (3)$$

Here, eqs. (1) and (3) are called the calculus with respect to monotone function [6].

The scaling-law calculus

Let $\psi(t) = [\psi \circ (\kappa t^\beta)](t) = \psi(\kappa t^\beta)$, where κ is the normalization constant and β is the scaling exponent [7, 9].

The scaling-law derivative of the function $\psi(t)$ is defined [7]:

$${}^{SL}D_t^{(1)}\psi(t) = \frac{1}{\beta \kappa t^{\beta-1}} \frac{d\psi(t)}{dt} \quad (4)$$

The scaling-law derivative of high-order is defined [6, 11]:

$${}^{SL}D_t^{(n)}\psi(t) = \left(\frac{1}{\beta \kappa t^{\beta-1}} \frac{d}{dt} \right)^n \psi(t) \quad (5)$$

where $n \in \mathbb{N}$.

The scaling-law integral of the function $\psi(t)$ is defined [9]:

$${}_a {}^{SL}I_t^{(1)}\psi(t) = \beta \kappa \int_a^t \psi(t) t^{\beta-1} dt \quad (6)$$

Here, eqs. (4) and (5) are called the scaling-law calculus [6, 7, 9].

Mandelbrot-scaling-law calculus

Let $\psi(t) = [\psi \circ (\kappa t^{1-D})](t) = \psi(\kappa t^{1-D})$, where κ is the normalization constant and D is the scaling exponent.

The Mandelbrot scaling-law function $\psi(t)$ is defined as [16]:

$$g(t) = \kappa t^{1-D} \quad (7)$$

where $\kappa \in \mathbb{R}_+$, $t \in \mathbb{R}_+$, and D is the fractal dimension with $D \in \mathbb{R}_+$.

The Mandelbrot-scaling-law derivative of the function $\psi(t)$ is defined:

$${}^{MSL}D_t^{(1)}\psi(t) = \frac{t^D}{(1-D)\kappa} \frac{d\psi(t)}{dt} \quad (8)$$

The Mandelbrot-scaling-law derivative of high-order is defined:

$${}^{MSL}D_t^{(n)}\psi(t) = \left[\frac{t^D}{(1-D)\kappa} \frac{d}{dt} \right]^n \psi(t) \quad (9)$$

where $n \in \mathbb{N}$.

The Mandelbrot-scaling-law integral of the function $\psi(t)$ is defined:

$${}^{MSL}I_a^{(1)}\psi(t) = (1-D)\kappa \int_a^t \psi(t) t^D dt \quad (10)$$

Here, eqs. (8) and (10) are called the Mandelbrot-scaling-law calculus.

The Mandelbrot-scaling-law partial derivative of the function $\psi(x, t)$ respect to the variable x is defined:

$${}^{MSL}\partial_x^{(1)}\psi(x, t) = \frac{t^D}{(1-D)\kappa} \frac{\partial \psi(x, t)}{\partial x} \quad (11)$$

and the Mandelbrot-scaling-law partial derivative of the function $\psi(x, t)$ respect to the variable t as:

$${}^{MSL}\partial_t^{(1)}\psi(x, t) = \frac{t^D}{(1-D)\kappa} \frac{\partial \psi(x, t)}{\partial t} \quad (12)$$

The indefinite Mandelbrot-scaling-law integral, which is called the antidifferentiation with respect to Mandelbrot-scaling-law function, is defined:

$${}^{MSL}I_t^{(1)}\psi(t) = (1-D)\kappa \int \psi(t) t^D dt = \Phi(t) + \mathcal{G} \quad (13)$$

which leads to:

$${}^{MSL}D_t^{(1)} \left[{}^{MSL}I_t^{(1)}\psi(t) \right] = {}^{MSL}D_t^{(1)} \left[\Phi(t) + \mathcal{G} \right] = {}^{MSL}D_t^{(1)}\Phi(t) = \psi(t) \quad (14)$$

and

$${}^{MSL}I_t^{(1)} \left[{}^{MSL}D_t^{(1)}\Phi(t) \right] = \Phi(t) + \mathcal{G} \quad (15)$$

where \mathcal{G} is the constant.

Let $\psi(t) = \Lambda(\kappa t^{D-1})$, $\psi_1(t) = \Lambda_1(\kappa t^{D-1})$, and $\psi_2(t) = \Lambda_2(\kappa t^{D-1})$ be continuous functions.

The properties of the Mandelbrot-scaling-law calculus can be given:

– (S1) The sum and difference rules for the Mandelbrot-scaling-law derivative:

$${}^{MSL}D_t^{(1)} \left[\psi_1(t) \pm \psi_2(t) \right] = {}^{MSL}D_t^{(1)}\psi_1(t) \pm {}^{MSL}D_t^{(1)}\psi_2(t) \quad (16)$$

where ${}^{MSL}D_t^{(1)}\psi_1(t)$ and ${}^{MSL}D_t^{(1)}\psi_2(t)$ exist.

- (S2) The constant multiple rule for the Mandelbrot-scaling-law derivative:

$${}^{MSL}D_t^{(1)}[\mu\psi(t)] = \mu {}^{MSL}D_t^{(1)}\psi(t) \quad (17)$$

where ${}^{SL}D_t^{(1)}\psi(t)$ exists and μ is a constant.

- (S3) The product rule for the Mandelbrot-scaling-law derivative:

$${}^{MSL}D_t^{(1)}[\psi_1(t)\psi_2(t)] = \psi_2(t) {}^{MSL}D_t^{(1)}\psi_1(t) + \psi_1(t) {}^{MSL}D_t^{(1)}\psi_2(t) \quad (18)$$

where ${}^{MSL}D_t^{(1)}\psi_1(t)$ and ${}^{MSL}D_t^{(1)}\psi_2(t)$ exist.

- (S4) The quotient rule for the Mandelbrot-scaling-law derivative:

$${}^{MSL}D_t^{(1)}\left[\frac{\psi_1(t)}{\psi_2(t)}\right] = \frac{\psi_2(t) {}^{MSL}D_t^{(1)}\psi_1(t) - \psi_1(t) {}^{MSL}D_t^{(1)}\psi_2(t)}{\psi_2(t)\psi_2(t)} \quad (19)$$

where ${}^{MSL}D_t^{(1)}\psi_1(t)$ and ${}^{MSL}D_t^{(1)}\psi_2(t)$ exist, and $\psi_2(t) \neq 0$.

- (S5) The chain rule for the Mandelbrot-scaling-law derivative:

$${}^{MSL}D_t^{(1)}\{w[\psi(t)]\} = \frac{dw(\psi)}{d\psi} {}^{MSL}D_t^{(1)}\psi(t) \quad (20)$$

where $dw(\psi)/d\psi$ and ${}^{MSL}D_t^{(1)}\psi(t)$ exist.

- (S6) The sum and difference rules for the Mandelbrot-scaling-law integral:

$${}^{MSL}I_t^{(1)}[\psi_1(t) \pm \psi_2(t)] = {}^{MSL}I_t^{(1)}\psi_1(t) \pm {}^{MSL}I_t^{(1)}\psi_2(t) \quad (21)$$

where ${}^{MSL}I_t^{(1)}\psi_1(t)$ and ${}^{MSL}I_t^{(1)}\psi_2(t)$ exist.

- (S7) The integration by parts for the Mandelbrot-scaling-law integral:

$${}^{MSL}I_t^{(1)}[\psi_2(t) {}^{MSL}D_t^{(1)}\psi_1(t)] = [\psi_1(t)\psi_2(t)]_a^t - {}^{MSL}I_t^{(1)}[\psi_1(t) {}^{MSL}D_t^{(1)}\psi_2(t)] \quad (22)$$

where $[\psi_1(t)\psi_2(t)]_a^t = \psi_1(t)\psi_2(t) - \psi_1(a)\psi_2(a)$.

- (S8) The sum and difference rules for the indefinite Mandelbrot-scaling-law integral:

$${}^{MSL}I_t^{(1)}[\psi_1(t) \pm \psi_2(t)] = {}^{MSL}I_t^{(1)}\psi_1(t) \pm {}^{MSL}I_t^{(1)}\psi_2(t) \quad (23)$$

where ${}^{MSL}I_t^{(1)}\psi_1(t)$ and ${}^{MSL}I_t^{(1)}\psi_2(t)$ exist.

- (S9) The integration by parts for the indefinite Mandelbrot-scaling-law integral:

$${}^{MSL}I_t^{(1)}[\psi_2(t) {}^{MSL}D_t^{(1)}\psi_1(t)] = \psi_2(t)\psi_1(t) - {}^{MSL}I_t^{(1)}[\psi_1(t) {}^{MSL}D_t^{(1)}\psi_2(t)] \quad (24)$$

The n – order Mandelbrot-scaling-law partial derivative of the function $\psi(x, t)$ respect to the variable x is defined:

$${}^{MSL}\partial_x^{(n)}\psi(x, t) = \left[\frac{t^D}{(1-D)\kappa} \frac{\partial}{\partial x} \right]^n \psi(x, t) \quad (25)$$

and the n – order Mandelbrot-scaling-law partial derivative of the function $\psi(x, t)$ respect to the variable t as:

$${}^{MSL}\partial_t^{(n)}\psi(x, t) = \left[\frac{t^D}{(1-D)\kappa} \frac{\partial}{\partial t} \right]^n \psi(x, t) \quad (26)$$

The Mandelbrot-scaling-law-telegraph models with the traveling-wave solution

The Mandelbrot-scaling-law-telegraph equation

Let us derive the Mandelbrot-scaling-law telegraph equation based on the Mandelbrot-scaling-law calculus.

The voltage across the resistor, which is derived from the well-known Ohm's law, is given:

$$u(x, t) = Ri(x, t) \quad (27)$$

where R is the resistance of the cable, $i(x, t)$ is the current on the cable at any point x and any time t , and $u(x, t)$ is the voltage on the cable at any point x and any time t .

The voltage drop across the inductor element via Mandelbrot-scaling-law derivative is given:

$$u(x, t) = L^{MSL} \partial_t^{(1)} i(x, t) = \frac{Lt^D}{(1-D)\kappa} \frac{di(x, t)}{dt} \quad (28)$$

which leads to:

$$u(x, t) = \frac{1}{L} {}^{MSL}I_t^{(1)} i(x, t) = \frac{(1-D)\kappa}{L} \int i(x, t) t^D dt \quad (29)$$

where L is denotes the inductance of the cable, κ is the normalization constant, and $D(0 \leq D \leq 1)$ is the fractal dimension.

The voltage drop across the capacitor element via Mandelbrot-scaling-law integral is given:

$$u(x, t) = \frac{1}{C} {}^{MSL}I_t^{(1)} \psi(t) = \frac{(1-D)\kappa}{C} \int i(x, t) t^D dt \quad (30)$$

which reduces to:

$$i(x, t) = C \partial_t^{(1)} u(x, t) = \frac{Ct^D}{(1-D)\kappa} \frac{du(x, t)}{dt} \quad (31)$$

where C denotes the inductance of the cable, κ is the normalization constant, and D is the fractal dimension.

In the telegraphic transmission line with leakage, we present:

$$\frac{\partial u(x, t)}{\partial x} = -Ri(x, t) - L^{MSL} \partial_t^{(1)} i(x, t) \quad (32)$$

In the current through leakage to the ground, we may give:

$$\frac{\partial i(x, t)}{\partial x} = -Gu(x, t) - C^{MSL} \partial_t^{(1)} u(x, t) \quad (33)$$

where G denotes the conductance to the ground.

Finding the Mandelbrot-scaling-law derivative of (32), we have:

$$\frac{\partial^2 u(x, t)}{\partial x^2} = -R \frac{\partial}{\partial x} i(x, t) - L^{MSL} \partial_t^{(1)} \left[\frac{\partial}{\partial x} i(x, t) \right] \quad (34)$$

Substituting eq. (33) into eq. (34), we have:

$$\frac{\partial^2 u(x,t)}{\partial x^2} = RG u(x,t) + (RC + LG)^{MSL} \partial_t^{(1)} u(x,t) + LC^{MSL} \partial_t^{(2)} u(x,t) \quad (35)$$

From eq. (35) we have:

$$\frac{\partial^2 u(x,t)}{\partial x^2} = RG u(x,t) + (RC + LG)^{MSL} \partial_t^{(1)} u(x,t) + LC^{MSL} \partial_t^{(2)} u(x,t) \quad (36)$$

which can be written as:

$$\frac{1}{LC} \frac{\partial^2 u(x,t)}{\partial x^2} = \frac{RG}{LC} u(x,t) + \frac{[RC + LG]}{LC}^{MSL} \partial_t^{(1)} u(x,t) + \partial_t^{(2)} u(x,t) \quad (37)$$

Thus, the Mandelbrot-scaling-law-telegraph model reads:

$$\theta^2 \frac{\partial^2 u(x,t)}{\partial x^2} = {}^{MSL} \partial_t^{(2)} u(x,t) + \gamma {}^{MSL} \partial_t^{(1)} u(x,t) + \rho u(x,t) \quad (38)$$

or

$$\theta^2 \frac{\partial^2 u(x,t)}{\partial x^2} = \left[\frac{t^D}{(1-D)\kappa} \frac{\partial}{\partial t} \right]^2 u(x,t) + \frac{\gamma t^D}{(1-D)\kappa} \frac{\partial u(x,t)}{\partial t} + \rho u(x,t) \quad (39)$$

where $\theta^2 = 1/(LC)$, $\rho = RG/(LC)$, and $\gamma = (RC + LG)/(LC)$.

The Mandelbrot-scaling-law-telegraph model can be repeated as:

$$\theta^2 \frac{\partial^2 u(x,t)}{\partial x^2} = a(\kappa) t^{2D} \frac{\partial^2}{\partial t^2} u(x,t) + b(\kappa) t^D \frac{\partial u(x,t)}{\partial t} + \rho u(x,t) \quad (40)$$

where $a(\kappa) = 1/[(1-D)^2 \kappa^2]$ and $b(\kappa) = \gamma/[(1-D)\kappa]$.

The traveling-wave solution

Let us consider the similar variable of Mandelbrot-scaling-law type, given:

$$z = x + \kappa t^{1-D} \quad (41)$$

where κ is the normalization constant, and D is the fractal dimension.

Taking $u(x,t) = u(z)$, we have from eq. (20) that:

$$\frac{\partial^2 u(z)}{\partial z^2} = \frac{\partial^2 u(x,t)}{\partial x^2}, \quad \frac{\partial u(z)}{\partial z} = {}^{MSL} \partial_t^{(1)} u(x,t), \quad \text{and} \quad \frac{\partial^2 u(z)}{\partial z^2} = {}^{MSL} \partial_t^{(2)} u(x,t), \quad (42a, b, c)$$

we have from eq. (38) that:

$$(\theta^2 - 1) \frac{d^2 u(z)}{dz^2} - \gamma \frac{du(z)}{dz} - \rho u(z) = 0 \quad (43)$$

with the well-known solution ($\mathcal{G} = [\gamma^2 + 4(\theta^2 - 1)\rho]^{1/2}$), given:

$$u(z) = \lambda_1 e^{\frac{\gamma + \mathcal{G}z}{2(\theta^2 - 1)}} + \lambda_2 e^{\frac{\gamma - \mathcal{G}z}{2(\theta^2 - 1)}} \quad (44)$$

where λ_1 and λ_2 are two constants.

Thus, the traveling-wave solution for eq. (38) can be given:

$$u(x, t) = \lambda_1 e^{\frac{\gamma + \theta x}{2(\theta^2 - 1)}} e^{\zeta t^{1-D}} + \lambda_2 e^{\frac{\gamma - \theta x}{2(\theta^2 - 1)}} e^{-\zeta t^{1-D}} \quad (45)$$

where $\zeta = \theta \kappa / [2(\theta^2 - 1)]$ and the Kohlrausch-Williams-Watts function is denoted as [6, 17, 18] $e^{-\zeta t^{1-D}} = \sum_{n=0}^{\infty} (-\zeta)^n t^{n(1-D)} / n!$ (For the more details for the functions related to the Kohlrausch-Williams-Watts function, see [6, 10]).

Conclusion

In this work, we addressed the Mandelbrot-scaling-law calculus to model the scaling-law telegraph models. The traveling-wave solution for the scaling-law telegraph equations was presented with the aid of the Kohlrausch-Williams-Watts function. The work may be used to describe the Brownian time and Mandelbrot-scaling-law behaviors in the circuit.

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Nomenclature

$i(x, t)$ – current on the cable, [A]
 t – time, [s]

$u(x, t)$ – voltage on the cable, [V]
 x – space co-ordinate, [m]

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