

A NEW METHOD SOLVING LOCAL FRACTIONAL DIFFERENTIAL EQUATIONS IN HEAT TRANSFER

by

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In this article, a new method, which is coupled by the variational iteration and reduced differential transform method, is proposed to solve local fractional differential equations. The advantage of the method is that the integral operation of variational iteration is transformed into the differential operation. One test examples is presented to demonstrate the reliability and efficiency of the proposed method.

Key words: variational iteration method, reduced differential transform method, local fractional differential equation

Introduction

In the last few decades, many types of fractional calculus have been introduced in [1]. However, most fractional derivatives are globally defined, so they are not suitable to reflect local geometric behaviors of a given function. Thence a few of local fractional derivatives [2-5] have been defined by modifying the definition of popular non-local fractional derivatives and making them local. Among these local fractional derivatives, one local fractional derivative [4] is developed to deal with non-differentiable functions defined on Cantor fractal space. The local fractional calculus [5] has been used to process many equations resulting from practical problems, for example, the non-linear local fractional FitzHugh-Nagumo and Newell-Whitehead equations [6], the fractal heat transfer in silk cocoon hierarchy [7], the electric circuit [8], the wave equation [9], *etc.* The list is obviously not complete. Many methods have been developed to find the analytic solutions of the local fractional differential equations, for example, the Yang-Fourier transforms method [10], the local fractional homotopy perturbation method [11], the fractional complex transform method [12], the local fractional Laplace series expansion method [13], the Sumudu transform and the variational iteration method [14], the Yang-Laplace method [15], the hybrid computational approach [16-18], *etc.* Among these methods, it is worth noting that the local fractional variational iteration method could be used to solve various types of local fractional differential equations. In this paper, by coupling the local differential transform method, we enrich the local fractional variational iteration method in the form of series, while maintaining the high accuracy of the method.

Preliminaries

In this section, we introduce some definitions and basic results of the local fractional differential calculus, which shall be applied in this article.

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Definition 1. The $\alpha(0 < \alpha \leq 1)$ order local fractional derivative of the function $\mathcal{G}(x)$ at x_0 is defined [4, 5]:

$$\mathcal{G}^{(\alpha)}(x_0) = D_x^{(\alpha)} \mathcal{G}(x_0) = \frac{d^\alpha \mathcal{G}(x)}{dx^\alpha} \Big|_{x=x_0} = \lim_{x \rightarrow x_0} \frac{\Gamma(1+\alpha) [\mathcal{G}(x) - \mathcal{G}(x_0)]}{(x-x_0)^\alpha} \quad (1)$$

Definition 2. In the interval $[c, d]$, the local fractional integral of $\mathcal{G}(t)$ of order $\alpha(0 < \alpha \leq 1)$ is defined [4, 5]:

$${}_c I_d^{(\alpha)} \mathcal{G}(t) = \frac{1}{\Gamma(1+\alpha)} \lim_{\Delta t \rightarrow 0} \sum_{j=0}^{j=N-1} \mathcal{G}(t_j) (\Delta t_j)^\alpha = \frac{1}{\Gamma(1+\alpha)} \int_c^d \mathcal{G}(t) (dt)^\alpha \quad (2)$$

where $\Delta t_j = t_{j+1} - t_j$ and, $j = 0, \dots, N-1$, $t_0 = c$, $t_N = d$ is a partition of the interval $[c, d]$.

Definition 3. The 2-D local fractional reduced differential transform $\Theta(k, m)$ of the function $\mathcal{G}(t, x)$ is defined by the following eq. [19]:

$$\Theta(k, m) = DT_{k,m} \{ \mathcal{G}(t, x) \} = \frac{1}{\Gamma(1+k\alpha)\Gamma(1+m\alpha)} \left[\frac{\partial^{k\alpha+m\alpha}}{\partial t^{k\alpha} \partial x^{m\alpha}} \mathcal{G}(t, x) \right]_{x=0, t=0} \quad (3)$$

where

$$\mathcal{G}(t, x) = \sum_{k=0}^{\infty} \sum_{h=0}^{\infty} \Theta(k, h) t^{k\alpha} x^{h\alpha} \quad (4)$$

The process of the new method

In this section, in order to present the technique and the process of the method coupled variational iteration and reduced differential transform method, we give the following local fractional differential equation:

$$\frac{\partial^{k_0\alpha}}{\partial t^{k_0}} \mathcal{G}(t, x) + L_\alpha \mathcal{G}(t, x) + R_\alpha \mathcal{G}(t, x) = \mu(t, x) \quad (5)$$

where L_α and R_α are linear and non-linear operator, respectively, which all have differential order less than $k_0(k_0 \geq 1)$ with respect to variable, and $\mu(t, x)$ is the source term.

In light of the local fractional variational iteration formula, the correction function for eq. (5) is constructed [4]:

$$\mathcal{G}_{n+1}(t, x) = \mathcal{G}_n(t, x) + {}_0 I_t^{(\alpha)} \left\{ \frac{\kappa^\alpha(\tau, t)}{\Gamma(1+\alpha)} \left[\frac{\partial^{k_0\alpha}}{\partial \tau^{k_0}} \mathcal{G}_n(\tau, x) + L_\alpha \tilde{\mathcal{G}}_n(\tau, x) + R_\alpha \tilde{\mathcal{G}}_n(\tau, x) - \mu(\tau, x) \right] \right\} \quad (6)$$

where $\kappa^\alpha(\tau, t)/\Gamma(1+\alpha)$ is a Lagrange multiplier.

If $\tilde{\mathcal{G}}_n(\tau, x)$ is a restricted variation, i. e. $\delta^\alpha \tilde{\mathcal{G}}_n(\tau, x) = 0$, according to [4], we can derive:

$$\frac{\kappa^\alpha(\tau, t)}{\Gamma(1+\alpha)} = \frac{(\tau-t)^{(k_0-1)\alpha}}{\Gamma[1+(k_0-1)\alpha]} \quad (7)$$

From eqs. (6) and (7) we can construct the following iteration procedure for eq. (5):

$$\mathcal{G}_{n+1}(t, x) = \mathcal{G}_n(t, x) + {}_0 I_t^{(\alpha)} \cdot \left\{ \frac{(\tau-t)^{(k_0-1)\alpha}}{\Gamma[1+(k_0-1)\alpha]} \left[\frac{\partial^{k_0\alpha}}{\partial \tau^{k_0}} \mathcal{G}_n(\tau, x) + L_\alpha \mathcal{G}_n(\tau, x) + R_\alpha \mathcal{G}_n(\tau, x) - \mu(\tau, x) \right] \right\} \quad (8)$$

Taking the mixed partial derivative with respect to the variables t and x on both sides of eq. (8), we can obtain:

$$\frac{\partial^{k\alpha+h\alpha}}{\partial t^{k\alpha} \partial x^{h\alpha}} \mathcal{G}_{n+1}(t, x) = \frac{\partial^{k\alpha+h\alpha}}{\partial t^{k\alpha} \partial x^{h\alpha}} \mathcal{G}_n(t, x) + \frac{\partial^{h\alpha}}{\partial x^{h\alpha}} \left\{ {}_0 I_t^{(\alpha)} \left[\frac{(\tau-t)^{(k_0-1)\alpha}}{\Gamma[1+(k_0-1)\alpha]} \left(\frac{\partial^{k_0\alpha}}{\partial \tau^{k_0}} \mathcal{G}_n + L_\alpha \mathcal{G}_n + R_\alpha \mathcal{G}_n - \mu(\tau, x) \right) \right] \right\}, \quad (0 \leq k \leq k_0 - 1) \quad (9)$$

where $\mathcal{G}_n = \mathcal{G}_n(\tau, x)$, and

$$\frac{\partial^{k\alpha+h\alpha}}{\partial t^{k\alpha} \partial x^{h\alpha}} \mathcal{G}_{n+1}(t, x) = -\frac{\partial^{k\alpha+h\alpha}}{\partial t^{k\alpha} \partial x^{h\alpha}} \left\{ {}_0 I_t^{(k_0\alpha)} [L_\alpha \mathcal{G}_n(\tau, x) + R_\alpha \mathcal{G}_n(\tau, x) - \mu(\tau, x)] \right\}, \quad (k \geq k_0) \quad (10)$$

According to eq. (9) and taking the 2-D local fractional reduced differential transform with respect to the variables t and x on both sides of eq. (8), we can obtain:

$$DT_{k,h} [\mathcal{G}_{n+1}(t, x)] = DT_{k,h} [\mathcal{G}_n(t, x)] = \dots = DT_{k,h} [\mathcal{G}_0(t, x)], \quad (0 \leq k \leq k_0 - 1) \quad (11)$$

where $\mathcal{G}_0(t, x)$ is an initial value.

With the use of eq. (10) and taking the 2-D local fractional reduced differential transform with respect to the variables t and x on both sides of eq. (8), we can obtain:

$$DT_{k,h} \{ \mathcal{G}_{n+1}(t, x) \} = -DT_{k,h} \left\{ {}_0 I_t^{(k_0\alpha)} [L_\alpha \mathcal{G}_n(\tau, x) + R_\alpha \mathcal{G}_n(\tau, x) - \mu(\tau, x)] \right\}, \quad (k \geq k_0) \quad (12)$$

According to eq. (3) and letting $\Theta(k, h) = DT_{k,h} \{ \mathcal{G}_n(\tau, x) \}$, $n = 0, 1, 2, 3, \dots$, we can rewrite eqs. (11) and (12), respectively:

$$\Theta_{T_{n+1}}(k, h) = \Theta_{T_0}(k, h), \quad (0 \leq k \leq k_0 - 1) \quad (13)$$

and

$$\Theta_{T_{n+1}}(k, h) = -\frac{\Gamma[1+(k-k_0)\alpha]}{\Gamma(1+k\alpha)} \Theta_{W_n}(k-k_0, h), \quad (k \geq k_0) \quad (14)$$

where

$$\Theta_{W_n}(k-k_0, h) = DT_{k-k_0,h} \{ W_n(t, x) \} = \frac{\frac{\partial^{(k-k_0+h)\alpha}}{\partial x^{(k-k_0)\alpha} \partial t^{h\alpha}} [W_n(t, x)]}{\Gamma[1+(k-k_0)\alpha] \Gamma(1+h\alpha)} \quad (15)$$

and where

$$W_n(t, x) = L_\alpha \mathcal{G}_n(t, x) + R_\alpha \mathcal{G}_n(t, x) - \mu(t, x) \quad (16)$$

Now, we are reminded of the following convergence conditions of the variational iteration method in [20]. If $\mathcal{G}_{n+1}(t, x)$ satisfies:

$$\| \mathcal{G}_{n+1}(t, x) - \mathcal{G}_n(t, x) \|_\alpha \leq \gamma^\alpha \| \mathcal{G}_n(t, x) - \mathcal{G}_{n-1}(t, x) \|_\alpha, \quad 0 < \gamma < 1 \quad (17)$$

where γ is a constant and $\| \cdot \|_\alpha$ is fractional operator norm, then $\lim_{n \rightarrow \infty} \mathcal{G}_n(t, x)$ converges and the convergence function is an exact solution of the eq. (5).

In conclusion, if $\mathcal{G}_{n+1}(t, x)$ satisfies eq. (17), the analytic solution of eq. (5) can be given by the following series form:

$$\begin{aligned} \mathcal{G}(t, x) &= \lim_{n \rightarrow \infty} \mathcal{G}_{n+1}(t, x) = \lim_{n \rightarrow \infty} \left\{ \sum_{h=0}^{\infty} \sum_{k=0}^{k_0-1} \Theta_{T_0}(k, m) t^{k\alpha} x^{h\alpha} + \sum_{h=0}^{\infty} \sum_{k=k_0}^{\infty} \Theta_{T_{n+1}}(k, h) t^{k\alpha} x^{h\alpha} \right\} \\ &= \sum_{h=0}^{\infty} \sum_{k=0}^{k_0-1} \Theta_{T_0}(k, m) t^{k\alpha} x^{h\alpha} - \lim_{n \rightarrow \infty} \sum_{h=0}^{\infty} \sum_{k=k_0}^{\infty} \frac{\Gamma(1+(k-k_0)\alpha)}{\Gamma(1+k\alpha)} \Theta_{W_n}(k-k_0, h) x^{k\alpha} t^{h\alpha} \end{aligned} \quad (18)$$

The method indeed provides an efficient tool to solve differential equation. Now, we consider the exact solution of the following linear differential equations:

$$\frac{\partial^{2\alpha} \mathcal{G}(t, x)}{\partial t^{2\alpha}} + \rho_1 \frac{\partial^{2\alpha} \mathcal{G}(t, x)}{\partial x^{2\alpha}} + \rho_2 \frac{\partial^\alpha \mathcal{G}(t, x)}{\partial t^\alpha} + \rho_3 \frac{\partial^\alpha \mathcal{G}(t, x)}{\partial x^\alpha} + \rho_4 \mathcal{G}(t, x) = 0 \quad (19)$$

where ρ_i , ($i = 1, 2, 3, 4$) are all constants. Obviously, eq. (19) is an essential special case of eq. (5).

By virtue of Eq. (8), the iteration algorithm is offered:

$$\mathcal{G}_{n+1}(t, x) = \mathcal{G}_n(t, x) + {}_0I_t^\alpha \left\{ \frac{(\tau-t)^{(\alpha)}}{\Gamma(1+\alpha)} \left[L_t^{(2\alpha)} \mathcal{G}_n + \rho_1 L_{xx}^{(2\alpha)} \mathcal{G}_n + \rho_2 L_t^{(\alpha)} \mathcal{G}_n + \rho_3 L_x^{(\alpha)} \mathcal{G}_n + \rho_4 \mathcal{G}_n \right] \right\} \quad (20)$$

where $\mathcal{G}_n = \mathcal{G}_n(\tau, x)$.

Taking local fractional reduced differential transform with respect to the variables t and x on both sides of eq. (20), we successively obtain systems of equations:

$$\begin{cases} DT_{k,h} [\mathcal{G}_{n+1}(t, x)] = -DT_{k-2,h} (\rho_1 L_{xx}^{(2\alpha)} \mathcal{G}_n + \rho_2 L_t^{(\alpha)} \mathcal{G}_n + \rho_3 L_x^{(\alpha)} \mathcal{G}_n + \rho_4 \mathcal{G}_n), & (k \geq 2) \\ DT_{k,h} [\mathcal{G}_{n+1}(t, x)] = DT_{k,h} [\mathcal{G}_0(t, x)], & (k = 0, 1) \end{cases} \quad (21)$$

Employing eq. (10), we rewrite eq. (21) as the following eqs. (22) and (23):

$$\begin{aligned} \Theta_{T_{n+1}}(k, h) &= -\rho_1 \frac{(h+1)\alpha(h+2)\alpha \Theta_{T_n}(k-2, h+2)}{k\alpha(k-1)\alpha} - \rho_2 \frac{(k+1)\alpha \Theta_{T_n}(k+1, h)}{k\alpha(k-1)\alpha} \\ &\quad - \rho_3 \frac{(h+1)\alpha \Theta_{T_n}(k, h+1)}{k\alpha(k-1)\alpha} - \rho_4 \frac{\Theta_{T_n}(k-2, h)}{k\alpha(k-1)\alpha}, \quad (k \geq 2) \end{aligned} \quad (22)$$

and

$$\Theta_{T_{n+1}}(k, h) = \Theta_{T_0}(k, h), \quad 0 \leq k \leq 1 \quad (23)$$

$$\begin{aligned} \mathcal{G}(t, x) &= \lim_{n \rightarrow \infty} \mathcal{G}_{n+1}(t, x) = \sum_{h=0}^{\infty} \sum_{k=0}^1 \Theta_{T_0}(k, h) t^{k\alpha} x^{h\alpha} - \\ &\quad - \lim_{n \rightarrow \infty} \sum_{h=0}^{\infty} \sum_{k=2}^{\infty} \left\{ \begin{aligned} &\rho_1 \frac{(h+1)\alpha(h+2)\alpha \Theta_{T_n}(k-2, h+2)}{k\alpha(k-1)\alpha} + \rho_2 \frac{(k+1)\alpha \Theta_{T_n}(k+1, h)}{k\alpha(k-1)\alpha} \\ &+ \rho_3 \frac{(h+1)\alpha \Theta_{T_n}(k, h+1)}{k\alpha(k-1)\alpha} + \rho_4 \frac{\Theta_{T_n}(k-2, h)}{k\alpha(k-1)\alpha} \end{aligned} \right\} t^{k\alpha} x^{h\alpha} \end{aligned} \quad (24)$$

An illustrative example

To illustrate the techniques presented in the previous section, we give the following example to demonstrate the effectiveness of our proposed method.

Consider the following local fractional Laplace equation:

$$\frac{\partial^{2\alpha} \mathcal{G}(t, x)}{\partial t^{2\alpha}} + \frac{\partial^{2\alpha} \mathcal{G}(t, x)}{\partial x^{2\alpha}} = 0 \quad (25)$$

subject to the initial condition:

$$\mathcal{G}(0, x) = 1 + \cos_{\alpha}(x^{\alpha}) \quad (26)$$

According to eqs. (22), (23), and (25) the following iteration relation can be derived:

$$\Theta_{T_{n+1}}(k, h) = -\frac{(h+1)\alpha(h+2)\alpha \Theta_{T_n}(k-2, h+2)}{k\alpha(k-1)\alpha}, \quad (k \geq 2) \quad (27)$$

and

$$\Theta_{T_{n+1}}(k, h) = \Theta_{T_0}(k, h), \quad (k = 0, 1) \quad (28)$$

By virtue of eq. (26), we take the initial value:

$$\mathcal{G}_0(0, x) = 1 + \cos_{\alpha}(x^{\alpha}) \quad (29)$$

From eq. (29), we derive:

$$\Theta_{T_0}(0, h) = \begin{cases} 2^{\alpha}, h = 0 \\ 0, h = 2l+1, l \in N \\ (-1)^l \frac{1}{\Gamma(1+h\alpha)}, h = 2l, l \in N, l \neq 0 \end{cases} \quad (30)$$

and

$$\Theta_{T_0}(1, h) = 0 \quad (31)$$

Using eqs. (27), (28), and (31), we can get:

$$\Theta_{T_{n+1}}(k, h) = 0, \quad k = 2p+1, \quad p \in N \quad (32)$$

Similarly, using eqs. (27), (28), and (30), we can get:

$$\Theta_{T_{n+1}}(0, h) = \begin{cases} 2^{\alpha}, h = 0 \\ 0, h = 2l+1, l \in N \\ (-1)^l \frac{1}{\Gamma(1+h\alpha)}, h = 2l, l \in N, l \neq 0 \end{cases} \quad (33)$$

$$\Theta_{T_{n+1}}(2, h) = \begin{cases} 0, h = 2l+1, l \in N \\ (-1)^l \frac{1}{\Gamma(1+2\alpha)\Gamma(1+h\alpha)}, h = 2l, l \in N \end{cases} \quad (34)$$

$$\Theta_{T_{n+1}}(4, h) = \begin{cases} 0, h = 2l+1, l \in N \\ (-1)^l \frac{1}{\Gamma(1+4\alpha)\Gamma(1+h\alpha)}, h = 2l, l \in N \end{cases} \quad (35)$$

Then, according to eqs. (32)-(35), we can induce:

$$\Theta_{T_{n+1}}(k, h) = \begin{cases} 2^\alpha, k = h = 0 \\ 0, k = 2p + 1 \\ 0, k = 2p, h = 2l + 1 \\ (-1)^l \frac{1}{\Gamma(1+k\alpha)\Gamma(1+h\alpha)}, k = 2p, h = 2l, p \neq 0 \end{cases} \quad (36)$$

where p and $l \in N$.

From eq. (24), the exact solution of eq. (25) can be given:

$$\mathcal{G}(t, x) = 1 + \frac{1}{2} [E_\alpha(t^\alpha) + E_\alpha(-t^\alpha)] \cos_\alpha(x^\alpha) \quad (37)$$

Conclusion

In this task, we tried to couple the local fractional variational iteration with reduced differential transform method for solving local fractional differential equations. The example shows that our method can be easier to analyze the convergence solution or approximate solution.

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Nomenclature

t – time co-ordinate, [s]
 x – space co-ordinate, [m]

Greek symbols
 α – fractal order, [–]
 $\mathcal{G}(t, x)$ – temperature distribution, [K]

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