THE FUTURE (AND THE PRESENT) OF MOTOR VEHICLE PROPULSION SYSTEMS

by

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Limited reserves of oil and the increasing environmental effect of its usage as a motor fuel represent global issue related to the constantly increasing number of motor vehicles. Therefore, the reduction of the fossil fuel consumed and the emission produced in internal combustion engines is the primary goal of the development of motor vehicle propulsion systems. In that sense, the present and the future of motor vehicles relies on hybrid drive systems, electric drive systems and drive systems which use hydrogen as a fuel (either by its combustion or by production of electric energy with the help of fuel cells). In this paper, the authors have presented the aforementioned motor vehicle propulsion systems by explaining their function and design, their basic elements and their functions. Authors have also analysed advantages and disadvantages of the mentioned propulsion systems in comparison to conventional internal combustion engine based systems, both technically and environmentally speaking, but also in relation to available infrastructure and energy resources.

Key words: hybrid vehicles, electric vehicles, fuel cells, hydrogen, fuel consumption, exhaust emission, internal combustion engine

Introduction

Nowadays, oil, coal and natural gas are three major energy sources. The share of sources such as nuclear energy, geothermal springs and wind is significantly smaller, whereas so-called alternative fuels and innovative technologies take only a small part. Unfortunately, oil is not a renewable source of energy. According to the forecast [1], drastic changes will happen in year 2040, fig. 1. By that time, the production of crude oil will increase, but it will be followed by a sudden decrease. Thus, it is expected that in 2100 major sources of energy will be coal, renewable liquid and gaseous biofuels, solar energy, wind energy, as well as hydropower and nuclear energy. Also, there is the problem of unequal distribution of oil as a natural resource – for many countries, it is an import energy source whose price varies.

Estimates from 2014 point to the fact that 98% of motor vehicles on the planet use internal combustion (IC) engines running on hydrocarbon-based fuels, whereby the aforementioned percentage will not significantly change in the following ten to fifteen years. According to the statistical data [2], the number of motor vehicles in the world in 2014 was over 1.23 billion, fig. 2. The number of vehicles in 1970 was approximately five times smaller and in only 16 years (by 1986) the number of vehicles has doubled. In 2009, the number of motor vehicles on the planet already exceeded 1 billion. In only five years (from 2009 to 2014), the number of vehicles increased by more than 200 million - more than 20%. It is estimated that, by

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the year of 2035, the number of vehicles on the planet will reach two billion [3]. Such a forecast comes with some concerns, because of the fact that limited sources of energy are being used, primarily oil, which still represents the world leading energy source for the motor vehicles, and also because of the global pollution of our planet due to exhaust emission of IC engines.

It should be emphasized that the research has shown that the increase in fuel consumption while driving is followed by the increase in harmful exhaust emission, but in different proportions for various emission components. For example, if the difference in fuel consumption caused by different driving techniques is 21%, the difference in emission can be 72% for HC and 48% for NO_x [4]. The content of CO₂ in exhausts is linearly proportional to the fuel consumption. According to the data provided by the U.S. Environmental Protection Agency, transporta-

tion represented 27% of total U.S. GHG emissions in 2015, 83% of which is caused by road vehicles [5]. Each litre of petrol combusted in the vehicle engine produces 2.35 kg of CO₂ on average, whereas each combusted litre of diesel releases in the atmosphere 2.69 kg of CO₂ on average [6]. Average passenger vehicle emits 4.7 tons of CO₂ over one year [6]. This clearly shows that fuel-efficient driving not only saves fuel, but also contributes to the environment protection. The CO₂ is present in the air as a natural constituent and it is not considered to be a pollutant in terms of exhaust emission of motor vehicles. However, it is considered one of the major causes of climate changes due to *greenhouse effect*. Atmospheric CO₂ levels rose to 395 parts per million in 2012, making the second highest jump since 1959, when the measurements of atmospheric CO₂ levels began [7]. The direct relationship between exhaust emission and human health points to the significance of the reduction of the emission produced by fuel combustion.

Limited sources of oil and increased exhaust emission of motor vehicles represent the global challenge for the researchers. The problems are solved by applying new solutions on existing IC engines, as well as by using alternative fuels such as liquefied petroleum gas, compressed natural gas, or certain kinds of biofuels.

However, a special way to solve the aforementioned problems is to develop and use modern solutions, such as hybrid vehicles, electric vehicles and vehicles running on hydrogen. This paper presents their propulsion systems.

Hybrid vehicles

The concept of the hybrid drive and its characteristics

A hybrid vehicle is each vehicle which converts two or more different types of energy into mechanical energy which is used to power the vehicle [8]. The most common are hybrid electric vehicles (HEV) using the internal combustion engine (petrol or diesel based) and the electric motor [9]. The combination of IC engines and hydraulic or pneumatic drive systems is rarely used, as well as some other variants which will not be discussed here. A task of the hybrid vehicle is to combine good characteristics of both propulsion systems and to reduce their negative characteristics to a minimum.

Considering its power output, IC engine has a small weight and it occupies a relatively small space, refuelling is quick and drive range is rather high. However, IC engines do not have a high efficiency ratio and their exhaust emission cannot be ignored. Also, the working range of IC engines in real exploitation is not the range of minimum specific fuel consumption (low engine speed with higher loads) and the torque values are usually low at low engine speed (which is the case when starting from the standstill, which is especially important for city driving) [10].



Figure 3. Torque curves for different types of drive units; *1 – hybrid drive, 2 – IC engine, 3 – electric motor*

Unlike the IC engines, the maximum torque of the electric motor is already available when the vehicle is started, which is very important for starting the vehicle from the standstill. Besides, the electric motor has zero harmful exhaust emission and its high efficiency ratio does not depend on load. On the other hand, electric motor with the same power output weigh more than corresponding IC engine, while required batteries also increase the weight of the vehicle and occupy space that would be used for passengers or cargo. The battery charging process is significantly slower compared to refuelling the tank with fossil fuel. The drive range is rather limited compared to the vehicle driven by IC engines. Figure 3 shows torque curves for different drive units.

According to the aforementioned advantages and disadvantages of electric motor and IC engine, as well as available torque values for different engine speed, it can be concluded that combining these two propulsion methods can lead to the following benefits [11]:

- the IC engine works only in the range of higher efficiency ratio, *i.e.* smaller specific fuel consumption,
- it is possible to use smaller displacement engines,
- when braking, a part of kinetic energy can be transformed into electric energy with the help of electric motor, which then works in generator mode, and
- due to higher efficiency ratio of IC engine, exhaust emission is reduced and, in some cases, power is provided only by the electric motor, which gives zero exhaust emission.

Although the hybrid vehicle was patented at the end of the 19^{th} century, its real development started at the end of the 20^{th} century because of the pollution and due to the increasing price of oil and its limited reserves.

The design of the hybrid drive

The IC engine, electric motor and transmission are components of the hybrid drive which enables conversion and flow of different forms of energy. Depending on its design, configuration of the hybrid drive system can be series, parallel, series-parallel, and with planetary transfer gear [12, 13].

Series configuration of the hybrid drive

In series hybrid drive, there is no mechanical connection between the IC engine and wheels. Wheels are driven only by the electric motor which can be powered by battery or the energy produced by the generator driven by the IC engine. The electric motor can also be used to produce the electric energy through regenerative braking and store it in the batteries. In that case, the energy of wheels is used to turn the rotor of the electric motor, which acts as a generator. Instead of converting kinetic energy into heat, one part is accumulated as electric energy. Figure 4



Figure 4. Series configuration: *1–IC engine, 2–fuel tank, 3–generator, 4–electric motor, 5–pulse-controlled inverter, 6–battery*

shows series configuration of the hybrid drive.

Series configuration of the hybrid drive has a number of advantages. There is no mechanical connection between the IC engine and the wheels, so the engine operation can be optimized with the highest possible efficiency ratio; *i.e.* the lowest possible fuel consumption and exhaust emission. It can be achieved if the engine runs at consistent speed and appropriate load. The fact that there is no mechanical connection with the driving wheels gives a possibility of installing high-speed engines such as gas turbines. Also, the IC engine and the generator can be placed anywhere in the vehicle. It is also possible to use smaller displacement (and because of that lighter)

engines, which additionally reduce the exhaust emission. The torque characteristic of electric motors does not require multi-speed transmission, which is also reflected on the weight of the vehicle. The aforementioned configuration allows the use of two or more smaller electric motors, one for each driving wheel, so there is no need to use differential gear. Series configuration of the hybrid drive system is simple compared to other configurations.

Series hybrid drive systems perform well when the vehicle is used for city driving with frequent stop-and-go operation. With fully charged batteries, the vehicle uses only energy stored in batteries. Slow speed driving through the city can also be achieved in pure electric mode. For these vehicles, only a small amount of fuel is needed to move the vehicle from a standstill. Some systems offer the possibility of charging the batteries via electric grid (*plug-in hybrid*), which additionally reduces the fuel consumption.

However, series configuration of the hybrid drive system has also its negative sides and the biggest one of all is multiple energy conversion and accompanying losses. The energy produced by the IC engine, where the first conversion from chemical/thermal energy into mechanical energy takes place, needs to convert two more time on its way to the driving wheels. In the generator, mechanical energy is first converted into electric energy, and then electric energy is converted into mechanical energy again on its way out of the electric motor, but with some losses. That is why the efficiency ratio of the generator and the electric motor is very important. Series hybrid drive requires batteries with greater capacity than the parallel hybrid drive systems (explained later in the text), which considerably increases the weight. The presence of the generator also increases the weight of the vehicle, as well as the price. Series hybrid drive performs poorly when driving at high speeds (*e.g.* on motorways) or up longer gradients because then they use electric energy produced only by the generator driven by the IC engine, which is not good because of the above-mentioned energy conversion and losses arisen.

Series configuration of the hybrid drive system is often used in heavy commercial vehicles and buses since they have more available space, as well as bigger and heavier batteries and generators. Some passenger cars can also be classified as series hybrid vehicles such as: Opel Ampera, Chevrolet Volt, BMW i3 and Fisker Karma.

Parallel configuration of the hybrid drive system

The major difference between the series and parallel configuration of the hybrid drive is that the parallel drive does not need energy conversion between the IC engine and electric motor, since it can use the energy from both sources at the same time. Both motors have mechanical connections with the driven wheels. In most concepts, the primary source of power is the IC engine, while the electric motor provides assistance in certain driving modes. There are also concepts which enable the vehicle to be propelled only by the electric motor. The electric motor can take over the role of the generator during regenerative braking. If, when working in the optimum mode, the IC engine delivers more power than it is needed to overcome resistance forces (which suits moderate driving modes), the surplus of power is used to recharge the battery.

Transfer gear can be a conventional gear or a planetary gear, chain or belt drive. Depending on the number of clutches, types of elements for power distribution, as well as the number of driving axles, there are several different variants of parallel configuration of the hybrid drive system.

Figure 5 shows the variant of parallel configuration with one clutch (and one shaft). The electric motor is directly connected to the internal combustion engine. Unlike the series configuration, the IC engine speed cannot be adjusted independently from electric motor speed. When the



Figure 5. Parallel configuration with one clutch; *1 – IC engine, 2 – fuel tank, 3 – electric motor/generator, 4 – clutch, 5 – pulse-controlled inverter, 6 – battery*

vehicle is slowing down, the IC engine cannot be disconnected from the electric motor, which has a negative impact on the regenerative braking effect. Pure electric driving mode is not possible for this variant, so the role of the electric motor is only to assist the IC engine.

The advanced variant of the parallel configuration has been achieved with two clutches (and one shaft) - additional clutch is added between the IC engine and the electric motor which enables switching the IC engine on and off when necessary, *i.e.* drive only via the electric motor. The IC engine can also be switched off when the vehicle is slowing down, which increases the potential of regenerative braking. In order to have a

shorter assembly, there is a solution with double clutch or two independent shafts - one for the IC engine and the other for the electric motor.

Parallel hybrid configuration is used in Honda Insight, Hyundai Ioniq Hybrid, Audi A3 Sportback e-Tron and Kia Optima Hybrid.

There is another parallel configuration of the hybrid drive, where one axle is driven by the IC engine, and the other one by the electric motor. This configuration has been classified as parallel, because the power outputs of the IC engine and the electric motor are combined. Apart from the all-wheel drive, it is also possible to distribute the torque per wheel in wide ranges. In order to provide constant all-wheel drive, there must be another generator driven by the existing IC engine. In that way, batteries can be additionally charged (not just by regenerative braking). Examples of this type of parallel hybrid are BMW i8 and Volvo V60 Hybrid.

The advantages of the parallel configuration of the hybrid drive system are reflected in the fact that the vehicle is driven using both engines, without the conversion of energy, *i.e.* with lower losses than in the series configuration. The design is more compact compared to the series configuration if there is no generator and because of the smaller electric motor. Therefore, this configuration can be used in smaller vehicles. The major disadvantage of this configuration is the fact that the IC engine and the electric motor are mechanically connected to the transmission and therefore the operation of the IC engine cannot be fully optimized. This type of systems requires complex management and complex transmission.

Series-parallel configuration

of the hybrid drive system

The series hybrid drive system has been extended into the series-parallel hybrid drive system, fig. 6, by establishing mechanical connection via the clutch between two electric motors, one of which operates only as a generator. The series-parallel hybrid drive system can use advantages of the series hybrid drive system at low speeds and avoid disadvantages at higher speeds when the clutch is switched on and when the series-parallel hybrid drive system operates like the parallel hybrid drive system.

Since the double conversion of energy is limited to the low range of speeds and power outputs, the series-parallel hybrid drive systems need smaller electric motors compared to the ones in the series hybrid drive systems. The series-parallel configuration is not as compact as the



Figure 6. Series-parallel configuration; *1 – IC engine, 2 – fuel tank, 3 – electric motor/generator, 4 – clutch, 5 – pulse-controlled inverter, 6 – battery*

series configuration and, in comparison with the parallel configuration, it requires an additional generator. Ford Fusion is the example of vehicle with this type of configuration.

The configuration of the hybrid drive with the planetary transfer gear

The configuration with the planetary transfer gear combines the characteristics of the parallel and series hybrid drive systems - it is most similar to the series-parallel configuration, so some sources in the literature refer to these two configurations as same. A part of the power of the IC engine is converted, with the help of the generator, into the electric Blagojević, I. A., *et al.*: The Future (and the Present) of Motor Vehicle Propulsion Systems THERMAL SCIENCE: Year 2019, Vol. 23, Suppl. 5, pp. ÙFÏ G ËJFÏ I H

energy and the rest of it, together with the power produced by the electric motor, is used to power the vehicle. The configuration with the planetary transfer gear is always a complete hybrid drive system, see tab. 1, because it enables all necessary functions (start/stop function, regenerative braking, hybrid drive and electrific-only drive).

The design is shown in fig. 7. The planetary transfer gear connects the IC engine, the generator and the electric motor by using its three elements (sun gear, planet carrier and ring gear). In that way IC engine speed can be adjusted within optimum limits, regardless of the vehicle speed.

A part of the power of the IC engine is mechanically transmitted, via the planetary



Figure 7. Configuration with planetary transfer gear; *1* – *IC engine*, *2* – *fuel tank*, *3* – *planetary transfer gear*, *4* – *electric motor/generator*, *5* – *pulse-controlled inverter*, *6* – *battery*

transfer gear, to the driven wheels. The rest of the power is transmitted to the driven wheels electrically, with double conversion of energy. Similarly to the series hybrid drive system, pure electric transmission can be used if the vehicle needs small amount of power. However, random switching between mechanical and electric drive systems is not possible. In this way, the hybrid drive system with the planetary transfer gear can significantly save fuel at low and medium speeds. Further fuel savings at high speeds are not possible.

The advantages of this configuration are: the operation of the IC engine is controlled so that its performance is optimum for the given conditions; the IC engine can drive the wheels and recharge the battery at the same time; with the help of both drive units the vehicle can achieve higher acceleration; in city conditions the vehicle can function as a vehicle with the series hybrid drive system and minimum air pollution or as a pure electric vehicle with zero emission. The complex kinematics of the transmission mechanism (transfer gear), a great number of components and the high weight, as well as a very complex management algorithm are disadvantages of this configuration.

The best representative of this configuration is Toyota Synergy Drive system which is implemented in all hybrid models manufactured by Toyota Motor Corporation.

Classification of hybrid vehicles by their functions and driving modes (levels of hybridization)

Beside the classification according to the design of the hybrid drive, there is another important classification of hybrid vehicles - by the level (degree) of hybridization or functions which the HEV can perform. The functions and driving modes are:

Start/stop function – it switches the IC engine off when the vehicle is not moving (a traffic jam, red traffic light *etc.*); the electric motor starts rotating the crankshaft of the IC engine at optimum speed; the engine start is almost instant; the source of energy for the electric motor is the battery which can be recharged by regenerative braking or by the electric motor operating as the generator driven by the IC engine; the electric motor can also keep the vehicle accessories working while the IC engine is at standstill.

Regenerative braking mode – when the vehicle is slowing down, a part of kinetic energy is converted into electric energy by the electric motor operating as the generator driven by the wheels,

conventional (hydraulic) braking system is still present in order to enable necessary performance, but the amount of energy which is converted into heat, by mechanical friction is smaller.

Hybrid driving mode – in hybrid mode, both the IC engine and the electric motor provide the necessary torque. It should be emphasized that, in this mode, a part of the torque of the IC engine can be, apart from propelling the vehicle, used to start the generator and produce the electric energy to feed the electric motor, *i.e.* to charge the battery.

Pure electric driving mode – in this driving mode, the vehicle moves only using electric energy without the harmful exhaust emission and with reduced noise level.

Recharging batteries at charging stations – it is possible to connect some hybrid vehicles, via appropriate charging inlet, to the electric network in order to recharge their batteries, such vehicles are called plug-in HEV.

Based on the functions and modes supported by the HEV, they have been classified by the level of hybridization, tab. 1.

Functions/modes	Levels of hybridization			
	Micro hybrid	Mild hybrid	Full hybrid	Plug-in hybrid
Start/stop	•	•	•	•
Regenerative braking	•	•	•	•
Hybrid mode		•	•	•
Electric mode			•	•
Recharging at charging stations				•

Table 1. The levels of hybridization according to the vehicle functions/modes

According to some studies, micro hybrid can save between 4% and 5% of fuel, mild hybrid between 10% and 15%, and full hybrid between 20% and 30%, while, naturally, plug-in hybrid saves the largest amount of fuel (between 50% and 70%), but without the amount of consumed electric energy taken into account [14].

Electric vehicles

Electric vehicles are motor vehicles driven by the electric motor fed from the electrochemical source of electric energy. Electric vehicles do not pollute the environment and they can be called zero emission vehicles. This section will focus only on electric vehicles with their own batteries, whereas the vehicles with the system for the production of electric energy with the help of fuel cells will be analysed in the following section that focuses on hydrogen as a fuel.

Electric vehicles have a number of advantages over the vehicles with IC engines: zero exhaust emission, significantly lower noise level, minimum operating vibrations, smooth start at low temperatures, instant availability of maximum torque, high energy efficiency ratio, low maintenance costs, low running costs, extremely good drive characteristics of the electric motor with allowed overloads, no dependence on oil products and possibility of using domestic energy resources. However, electric propulsion systems have certain disadvantages compared to conventional vehicles: smaller driving range and speed (in most cases), higher vehicle weight and less free space because of the battery, slow battery recharging and the need for battery-charging network [15, 16].

Components of electric

propulsion system and its design

Generally speaking, basic components of electric propulsion system are: electric motor, batteries with recharging system, electronic control unit and transmission system. These basic

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components with accompanying elements are functionally interconnected in order to form a specific electric vehicle architecture. A typical solution is presented in fig. 8 [17], with major possible deviations in the transmission systems, as explained later on in greater detail.



Figure 8. Design of electric drive system with components [17]; 1 – electric motor (generator), 2 – transmission system, 3 – electronic control unit for electric motor management (controller), 4 – high-voltage lines, 5 – high-voltage battery, 6 – inverter with electronic control unit for battery operation and charging, 7 – cooling system, 8 – brake system (including regenerative braking), 9 – high-voltage AC compressor, 10 – heating system, 11 – battery charger, 12 – charging inlet, 13 – external source of electric energy for battery recharging

Electric motor

There is a great variety of motors in electric vehicles, but the ones used most frequently are three-phase AC motors - induction asynchronous motors and permanent-magnet synchronous motors - as well as DC motors with brushes or without brushes (permanent magnet).

The selection of the electric motor is a very important step and it depends on preferred levels of performance, vehicle concept and characteristics of the battery. Permanent-magnet motors are becoming increasingly popular because of the high current density, *i.e.* because of the favourable power characteristics and compact design, even though their management

algorithms are complicated. On the other hand, DC motors are easier to install, more reasonablypriced and more suitable for short-term accelerations at lower speeds. Disadvantages are: the increase in operating temperature, possible uncontrolled increase in engine speed and poor characteristics in generator mode. Because of that, AC motors are the first choice. The characteristic of all electric motors is significantly higher efficiency (sometimes over 95%) compared to IC engines [18]. It is already mentioned that the torque curve of electric motors is more suitable for vehicle propulsion than the torque curve of conventional IC engines, since it is highest at the lowest engine speeds, which is of great significance when starting the vehicle from the standstill, as well as for overcoming gradient.

Transmission system and

design of the drive system

There are several solutions for the design of the electric vehicle propulsion system [19]: from solutions which strongly resembles the conventional vehicle with the IC engine, which means that there is an electric motor connected to the multi-speed gearbox with a clutch, to solutions where the wheel has its own drive unit which enables its independent propulsion, where power transmission elements are not necessary. The need for a multi-speed gearbox or just a fixed-ratio reduction gear depends on the purpose of the vehicle and preferred vehicle performance and on the characteristics of the electric motor itself. In all cases with one electric motor, it is necessary to have a differential gear and drive shafts, whereas, in case of one electric motor per wheel (on one or two axles), these elements are redundant.

Figure 9 shows possible designs of electric propulsion system with suitable transmission systems: Case (a) shows the variant of the electric vehicle whose transmission system does

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Figure 9. Possible designs of electric propulsion system with an appropriate transmission; M - electric motor, C - clutch, G - gearbox, RG - reduction gear, D - differential gear

not essentially differ from the transmission system of conventional vehicles with IC engines; Case (b) shows the variant where there is no clutch and the gearbox, but only one additional gear with fixed ratio (reduction gear), the advantage of this transmission system is reduction in vehicle weight, which allows implementation of a more complicated electric motor management system for providing necessary torque; Case (c) does not essentially differ from the Case (b), but in this variant, motor, additional gear and differential gear are within one assembly; Case (d) is the variant with two motors, in this configuration, the difference in engine speed of the left and right wheel is managed by electric motor management system, in order to avoid mechanical transmission and reduce losses, electric motors can be installed in wheels; Case (e)

shows the concept where there is an additional reduction gear next to the motor in the wheel, due to the high speed of the electric motor, its compact design and the possibility of input-output alignment, planetary gears are always applied in cases like these; Case (f) also shows the variant with the motor in the wheel, but without any mechanical transmission, in this case, different electric motors are used with significantly more complex algorithms for their management, the same principle is applicable on wheels of the other axle, consisting the all-wheel drive system.

Hydrogen propelled vehicles

Nowadays, hydrogen is one of the most interesting solutions for propelling motor vehicles even though, it is still far from mass usage. Many car manufacturers have presented their prototypes and models driven by hydrogen with the aim to emphasize that there is a potential in it.

The greatest advantage of hydrogen is the fact that it does not pollute the environment. It does not emit carbon in any form, which also applies to CO, NO_x or particulates. The major disadvantage is the high price of vehicles constructed to be propelled by hydrogen. Also, the great problem is the infrastructure - starting from the hydrogen factories to hydrogen filling stations. The production of hydrogen is, depending on the process used, up to seven times more expensive than the production of petrol and similarly costed diesel [20]. The fact that car manufacturers are interested in this technology and its improvement is encouraging, so it is rightfully expected that in the future the process of hydrogen production will be significantly cheaper. Another disadvantage of the hydrogen is that its production through the process of electrolysis requires electricity, which is likely to be most often produced by environment-unfriendly processes. If the hydrogen is to be a true environment-friendly source of energy, the electricity used for its production must be generated by environment-friendly processes such as solar, wind, tidal, hydroelectric or similar schemes.

There are two types of hydrogen vehicles: vehicles using hydrogen as direct energy source and vehicles using fuel cells. The former use IC engines which have been modified com-

pared to standard petrol engines and which combust hydrogen in the same way the petrol is combusted. However, the most popular hydrogen vehicles nowadays are the ones using fuels

Propulsion using hydrogen combustion in IC engines

cells.

Hydrogen can also be used in conventional petrol engines as its flame spreads quickly from the ignition core throughout the chamber. However, due to smaller energy density of hydrogen compared to petrol, at pressures suitable for cylinder pistons, engine displacement must be two or even three times bigger than of petrol engines (around 4 litres and 8 to 12 cylinders are needed), which is a problem in terms of space for its accommodation. The comparative overview of some characteristics of hydrogen and petrol has been presented in tab. 2 [21, 22].

Characteristic	Hydrogen	Gasoline	Unit
Minimum ignition energy in air	0.018	0.2-0.3	mJ
Flame temperature	2207	2307	°C
Autoignition temperature	575-580	480-550	°C
Flame velocity in air ($\lambda = 1$) at 20 °C and atmospheric pressure	2.37	0.12	m/s
Octane number	> 130	90-98	-
Flammability limits in air	4.1-75.6	1.48-2.3	% of volume

 Table 2. Comparative overview of certain characteristics of hydrogen and petrol in IC engines

Since large amounts of hydrogen are required in relation to the engine displacement, hydrogen needs to be much denser than it is possible in its gaseous form. Therefore, it is necessary to use liquid hydrogen cooled down to the temperature of 20 K, as well as special filling stations. Such technologies are already being developed and special tanks for liquid hydrogen have already been designed (with several layers of metal cylinders with appropriate insulation). However, it is also necessary to solve the problems of heat dissipation and hydrogen leakage.

Hydrogen as motor fuel is easier to use in public transportation vehicles. The engine and tank size problems are relatively easy to solve on city buses because of more space, including roof.

Hydrogen propulsion using IC engine can be achieved by modifying existing engine in a certain way: valve thermal treatment, usage of non-platinum tip spark plugs, higher coil voltage, injectors designed for gas (not liquid) usage, more durable gasket materials, higher temperature engine oils *etc*. Many manufacturers have experimented with hydrogen engines. Mazda has developed Wankel engine for hydrogen combustion, the Austrian company Alset has developed hybrid hydrogen/petrol system for Aston Martin Rapide S vehicle which participated in 24 Hours Nürburgring race [23] and BMW has developed their own supercar reaching the speed of 301 km/h burning hydrogen [24].

Propulsion using fuel cells

The increasingly popular technology widespread with hydrogen cars is the fuel cell technology. The fuel cell converts chemical energy into electric energy with the help of chemical reaction of positively-charged ions of hydrogen with oxygen or another oxidation agent. It is important to distinguish fuel cells from batteries, because fuel cells need the flow of fuel

and oxygen (air) in order to maintain the chemical reaction and produce electricity. This continuity in the production of electricity, as long as the fuel cell is supplied with fuel and oxygen (air), is its advantage.

There are many types of fuel cells [25], but the principle of their operation is essentially the same. Each of them has a cathode, an anode and an electrolyte which enable positivelycharged hydrogen ions to flow inside the fuel cell. The cathode and anode have the catalyst which causes the fuel reaction so that it can generate positively-charged ions and electrons. While the hydrogen ions flow through the electrolyte after the reaction, electrons flow from the anode to the cathode through the external circuit, thus producing direct current. Fuel cells are mostly classified by the type of used electrolyte and by the time of the reaction initiation, which can vary from one second to several minutes. Besides electricity, fuel cells produce water and heat, as well as the small amount of nitrogen oxides and other emissions depending on the used fuel.

In theory, fuel cells would function without losses, but that is not the case in real conditions. During their normal function, the major losses are: activation losses which directly depend on the degree of the chemical reaction, voltage drop due to the resistance of the medium to the flow of ions and electrons, and concentration losses depending on the reactant concentration and their changes. Theoretical voltage which fuel cell can achieve is around 1.2 V. However, due to the energy efficiency of the cell, which ranges from 40% to 60% [26], real operating voltage of the cell is between 0.45 and 0.72 V. Depending on the purpose of the fuel cells, they can be connected in two ways: in series (which produces higher voltage) or in parallel (which produces higher current). For motor vehicle propulsion, in order to gain maximum power output, fuel cells are arranged in such a way for the reacting gases to be uniformly distributed in all cells.

The type of electrolyte and its chemical composition determine the type of the fuel cell itself. The fuel it uses is also very important, but pure hydrogen is used most commonly. The anode catalyst, which is usually fine platinum powder, initiates the fuel and dissolves it into electrons and ions. Cathode catalyst, which is most often made of nickel, transforms ions into chemical compounds such as water or, rarely, dioxides of other elements. For the needs of hydrogen vehicle propulsion systems, fuel cells with polymer electrolyte membrane (PEM) represent an optimum choice because of their low operating temperature, which enables mobility essential for the vehicle.

At this point of hydrogen vehicles development, Toyota has made the greatest progress by presenting the first commercial vehicle model with fuel cells at the end of 2014. Toyota Mirai uses PEM fuel cells - there are 370 of them in the package, arranged in series. One fuel cell is 1.34 mm wide and has a mass of 102 g, whereas the total weight of all cells in the package is 56 kg. The curb mass of the vehicle is 1850 kg. Increased fuel-cell output voltage enables the reduction of the size of the electric motor, as well as of the number of fuel cells in the package. Hydrogen tank refilling typically takes 3 to 5 minutes and the vehicle with full tank can cover almost 500 km. This type of vehicle has two tanks made of plastic reinforced with carbon fibres, having a total mass of 88 kg. Fuel cells, arranged in a 3-D grid for better dispersion of oxygen, can have total maximum power output of 114 kW [27]. Current researches are pointed at making the fuel cells more efficient fuel using advanced control strategies [28, 29].

Fuel cell and battery electric vehicles compared

The transition to a more sustainable personal transportation sector requires the widespread adoption of electric vehicles powered by batteries (battery electric vehicles – BEV) or fuel cells (fuel cell vehicles – FCV). Automotive manufacturers are now confronted with decisions to invest in technologies that will become adopted in the future. While some manufacturers have chosen to invest in either BEV or in FCV, most companies have invested in both and/or have formed partnerships to develop both batteries and fuel cells. Academic literature has not yet sufficiently addressed the battle between BEV and FCV [30].

All-electric vehicles, either powered by batteries or by hydrogen fuel cells based on hydrogen produced from renewable energy seem to be the only viable option to meet the future CO₂ emission targets of less than 95 of g/km. An analysis of the system-level energy density of lithium-ion batteries (LiB) suggests that the gravimetric energy density of advanced LiB is unlikely to exceed 0.25 kWh/kg, which would limit the range of BEV for the compact car to cca. 200 miles (320 km), with recharging times substantially larger than that of conventional vehicles. Higher energy densities would only be possible if one were able to develop durable and safe metallic lithium anodes. While the so-called post-LiB, lithium-air and lithium-sulphur batteries have been assumed to revolutionize battery energy storage, cell- and system-level gravimetric energy densities will most definitely be lower. In contrast to BEV, hydrogen powered FCV are capable of large driving ranges (more than 480 km) and can be refilled within several minutes. Besides the need for a hydrogen infrastructure based on hydrogen produced from renewable energy, a reduction of the platinum requirement per vehicle (currently 20-40 g Pt/FCV) still requires further development [31].

The importance of technological superiority is confirmed in the literature on the technology battle between BEV and FCV. The FCV are considered to suffer from hydrogen storage and safety issues [32-34]. The BEV face challenges in range, *i.e.* battery capacity, and long charging times [35-37]. These limitations to technological performance make BEV and FCV less attractive in the eye of potential buyers, posing a barrier to market acceptance. Batteries are widely used in a wide variety of appliances, whereas fuel cells remain relatively unknown to the broader audience. Batteries are simply a proven technology. Concerning the latter, academic literature [38-40] indicates many technical specifics that determine superiority of BEV, ranging from fuel costs and battery/fuel cell life cycle to the performance indicators, aforementioned and more advanced factors such as possibilities to use the car for energy storage. An additional consideration worth mentioning at this point is whether technological superiority will remain important. According to the one study [41], when the first commercial product has been introduced within a product category, technology related factors for standard dominance become less important and marketing and business strategies become increasingly relevant. In other words, once both options have proven themselves in the market, other factors may become more important.

International compatibility is considered critical for the success of BEV; the difference in charging systems reduces the attractiveness, and therefore, the adoption of BEV [37, 42, 43]. The scattered process of development (in time and space) and the current lack of compatibility standards have led car manufacturers to produce vehicles with their own electrical connector types for DC fast charging [44]. In contrast, FCV hardly have any compatibility issues between FCV and fuel dispensers as hydrogen dispensing nozzles adapt to car receptacles [45].

Renewable electricity was considered for charging BEV and the production of hydrogen, but still it is hard to call FCV environmentally optimal if they ultimately waste 78% of the net energy, fig. 10 [46]. Traditional electrolysis has an efficiency of around 70%, whereas a newer technology called proton exchange membrane electrolysis can reach 80%. The transport, storage and distribution of hydrogen cost about 26% of the energy. By contrast, BEV only have to contend with grid losses, which average around 5%. Once it is in the vehicle, hydrogen has an efficiency which ranges from 40% to 60% - much better than efficiency of a gas or diesel engine, but lower than the 75% for a BEV. So FCV are less efficient than BEV at every stage of the process: generating hydrogen; transportation and storage; and converting it back to energy in the vehicle.

In the future, a hydrogen infrastructure is likely to be set up for heavy duty vehicles, and in the water and air transportation, which might enable an easy addition of fuel stations for personal transportation. However, as this infrastructure still needs to be built, and the electricity grid and an increasing number of charging stations are already in place, it is not surprising that experts



Figure 10. Overall energy efficiency BEV vs. FCV [46]

believe that BEV still have a substantial advantage over FCV [47]. In addition, the relative presence of BEV on the road compared to relatively few FCV could be responsible for a bias among experts that BEV have substantially fewer problems related to compatibility.

Conclusions

Almost all forecasts, even the ones from the end of the previous century, have anticipated a significantly greater usage of electric vehicles in the first two decades of 21st century, but that failed to materialise. The reasons for this might be partly attributed the so-called fossil fuels *lobby*, but the major factors are quite obvious - high prices of today's electric vehicles (despite government grants and untaxed energy supplies), their low range, long charging times and undeveloped infrastructure of charging stations. The actual environmental effects of electric vehicles should also be taken into consideration. In countries where electric energy is mostly generated from renewable sources of energy (water, wind, tidal and solar energy), electric vehicles can be considered as vehicles with zero emission. However, there are not many countries that can make such claims. For instance, in countries like Serbia, where most of the electric energy is generated by burning coal, the local emission is simply transferred elsewhere - from the vehicle operation areas to the powerplant sites. The emitted amount of CO, during the production of electric energy needed to power the electric vehicle can be just slightly smaller or in some cases even bigger than the amount that IC engine would emit. There would also be a problem of capacity for production of electric energy if most of the vehicles had electric drive systems. Finally, the self discharge of the batteries needs to be taken into consideration, and even more their environmental impact in production and recycling, which can be substantial.

It is clear that future solutions must also overcome many obstacles standing in the way of commercialization of hydrogen as a motor fuel. First of all, it implies the reduction of hydrogen production and transport costs, as well as building of a well-spread network of filling stations. Experts anticipate that, despite the presence of certain models, the mass production of hydrogen vehicles will not start in the following 15 years. However, hydrogen, being the most widespread

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chemical element, is to be potentially considered as a very promising energy source for vehicle propulsion.

Of all aforementioned vehicles, the ones with the hybrid-electric drive are most widespread, even though together with electric vehicles they do not reach even 1% of the total number of motor vehicles in the world. Still, the number of hybrid vehicles has significantly increased in the last 10 years. What also helps is the fact that future users are stimulated by various incentives. Besides, the use of hybrid vehicles does not have any particular disadvantages such as the undeveloped infrastructure of charging stations (excluding plug-in hybrid vehicles) or a very high purchase price. Unlike electric and hydrogen vehicles, hybrid vehicles cannot be considered as zero exhaust emission vehicles, but the environmental advantage they have over traditional IC engine vehicles must not be disregarded. In that sense, the hybrid drive should be regarded as an acceptable temporary solution which will be, with technological development and solutions to above-mentioned problems, gradually replaced by electric and/or hydrogen propulsion system.

Several major vehicle manufacturers have announced that, in the following 5 to 10 years, they would completely switch to hybrid and/or electric propulsion systems. However, numerous forecasts on the destiny of IC engines for vehicle propulsion have not come true. Scientific and technological development are necessary but not a sufficient condition to solve the problems which are complex and numerous in the near future. Considerable further work is needed in many areas and vehicle development and usage must be tailored to specific circumstances. Ultimately, environmental awareness of all citizens remains indispensable.

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