### MONTE CARLO METHOD FOR SOLVING A PARABOLIC PROBLEM

by

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In this paper, we present a numerical method based on random sampling for a parabolic problem. This method combines use of the Crank-Nicolson method and Monte Carlo method. In the numerical algorithm, we first discretize governing equations by Crank-Nicolson method, and obtain a large sparse system of linear algebraic equations, then use Monte Carlo method to solve the linear algebraic equations. To illustrate the usefulness of this technique, we apply it to some test problems.

Key words: Monte Carlo method, Crank-Nicolson method, system of linear algebraic equations

## Introduction

Recently there are many methods to solve heat conduction equations that are used for characterization thermal problems, Tian *et al.* [1] combined the Crank-Nicolson and Monte Carlo methods to solve a class of heat conduction equations. Jia *et al.* [2] used the semi-inverse method to establish a variational principle for an unsteady heat conduction equation. Liu *et al.* [3] adopted He's fractional derivative to study the heat conduction in fractal medium.

In this paper, we will consider a problem of determining an unknown function in the heat conduction equation:

$$u_t = a(t)u_{xx} = f(x,t), \quad 0 \quad x = 1, \quad t = 0$$
 (1)

with initial condition  $u(x, 0) = \varphi(x)$ , 0 < x < 1, and boundary conditions u(0, t) = a(t),  $u(1, t) = \beta(t)$ , t > 0, where a(t) > 0 is a known function and  $\varphi(x)$ , a(t),  $\beta(t)$ , and f(x, t) are known continuous functions.

The Crank-Nicolson method is employed to discretize the problem domain. Owing to the application of the Crank-Nicolson method, a large sparse system of linear algebraic equations is obtained, then we use Monte Carlo method to solve large systems of linear algebraic equations AX = b, where  $A = R^n$ , and  $A = R^n$  [4]. Monte Carlo algorithms have many advantages. For one thing, these algorithms are parallel algorithms, they have high parallel efficiency [5], for another thing, Monte Carlo methods are preferable for solving large sparse systems of linear algebraic equations, such as those arising from approximations of partial differential equation [6-9].

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#### Crank-Nicolson method for discretization

The domain [0, 1] [0, T] is divided into an n N mesh with the spatial-step size h = 1/n in the x direction and the time-step size  $\tau = T/N$ , respectively. Grid points  $(x_i, t_k)$  are defined by  $x_i = ih$ ,  $t_k = k\tau$ ,  $(0 \ i \ n, 0 \ k \ N)$ . The notation  $u_i^k$  is used for the finite difference approximation of  $u(ih, k\tau)$ . We define the operators:

$$u_{i}^{k-1/2} = \frac{1}{2} (u_{i}^{k} - u_{i}^{k-1}), \delta_{t} u_{i}^{k-1/2} = \frac{1}{\tau} (u_{i}^{k-1} - u_{i}^{k}), \delta_{x}^{2} u_{i}^{k}$$

$$= \frac{1}{h^{2}} (u_{i-1}^{k} - 2u_{i}^{k} - u_{i-1}^{k}), \delta_{x} u_{i}^{k} = \frac{1}{h} (u_{i-1/2}^{k} - u_{i-1/2}^{k})$$

Let's consider eq. (1) at point  $(x_i, t_{k+1/2})$ :

$$\frac{\partial u}{\partial t}(x_i, t_{k-1/2}) \quad a(t_{k-1/2}) \frac{\partial^2 u}{\partial x^2}(x_i, t_{k-1/2}) \quad f(x_i, t_{k-1/2})$$
 (2)

by Taylor's formula:

$$\frac{\partial^{2} u}{\partial x^{2}}(x_{i}, t_{k-1}) \quad \frac{\partial^{2} u}{\partial x^{2}}(x_{i}, t_{k-1/2}) \quad \frac{\partial^{3} u}{\partial x^{2} \partial t}(x_{i}, t_{k-1/2})(t_{k-1} - t_{k-1/2}) \\
\frac{1}{2!} \frac{\partial^{4} u}{\partial x^{2} \partial t^{2}}(x_{i}, \xi_{ik})(t_{k-1} - t_{k-1/2})^{2}, \quad t_{k-1/2} - \xi_{ik} - t_{k-1}$$
(3)

and

$$\frac{\partial^{2} u}{\partial x^{2}}(x_{i}, t_{k}) \quad \frac{\partial^{2} u}{\partial x^{2}}(x_{i}, t_{k-1/2}) \quad \frac{\partial^{3} u}{\partial x^{2} \partial t}(x_{i}, t_{k-1/2})(t_{k} - t_{k-1/2}) \\
\frac{1}{2!} \frac{\partial^{4} u}{\partial x^{2} \partial t^{2}}(x_{i}, \xi_{ik})(t_{k} - t_{k-1/2})^{2}, \quad t_{k} - \xi_{ik} - t_{k-1/2}$$
(4)

hence

$$\frac{\partial^2 u}{\partial x^2}(x_i, t_{k-1/2}) \quad \frac{1}{2} \quad \frac{\partial^2 u}{\partial x^2}(x_i, t_k) \quad \frac{\partial^2 u}{\partial x^2}(x_i, t_{k-1}) \quad \frac{\tau^2}{8} \quad \frac{\partial^4 u}{\partial x^2 \partial t^2}(x_i, \zeta_{ik})$$
 (5)

where 1 i n-1, k 0, and  $t_k < \zeta_{ik} < t_{k+1}$ . Similarly, we have:

$$\frac{\partial u}{\partial x^2}(x_i, t_{k-1/2}) \quad \delta_t u_i^{k-1/2} \quad \frac{\tau^2}{24} \frac{\partial^3 u}{\partial t^3}(x_i, \eta_{ik}), \quad t_k \quad \eta_{ik} \quad t_{k-1}$$
 (6)

and

$$\frac{\partial^2 u}{\partial x^2}(x_i, t_k) \quad \delta_x^2 u_i^k \quad \frac{h^2}{12} \frac{\partial^4 u}{\partial x^4}(\xi_{ik}, t_k), \quad t_k \quad \xi_{ik} \quad t_{k-1}$$
 (7)

Take eqs. (5)-(7) into (2), we obtain:

$$\delta_i u_i^{k-1/2} = a(t_{k-1/2}) \delta_x^2 u_i^{k-1/2} = f(x_i, t_{k-1/2}) = R_{ik}$$
 (8)

where

$$R_{ik} = \frac{1}{24} \frac{\partial^{3} u}{\partial t^{3}} (x_{i}, \eta_{ik}) = \frac{a(t_{k-1/2})}{8} \frac{\partial^{4} u}{\partial x^{2} \partial t^{2}} (x_{i}, \zeta_{ik}) \tau^{2}$$
$$= \frac{a(t_{k-1/2})}{24} \frac{\partial^{4} u}{\partial x^{4}} (\xi_{ik}, t_{k}) = \frac{\partial^{4} u}{\partial x^{4}} (\xi_{i,k-1}, t_{k-1}) h^{2}$$

Omit  $R_{ik}$  from eq. (8), consider initial condition and boundary conditions at point  $(x_i, t_k)$ , we have:

$$\delta_i u_o^{k-1/2} = a(t_{k-1/2}) \delta_x^2 u_i^{k-1/2} = f(x_i, t_{k-1/2}), \quad 1 = i \quad n = 1, \quad k = 0$$
 (9)

with  $u_i^0 = \varphi(x_i)$ , 0 i n, and  $u_0^k = \alpha(t_k)$ ,  $u_n^k = \beta(t_k)$ , k 0. According to eq. (9), we have:

$$\frac{a(t_{k-1/2})r}{2}u_{i-1}^{k-1} \quad [1 \quad a(t_{k-1/2})r]u_i^{k-1} \quad \frac{a(t_{k-1/2})r}{2}u_{i-1}^{k-1}$$

$$\frac{a(t_{k-1/2})r}{2}u_{i-1}^{k} \quad [1 \quad a(t_{k-1/2})r]u_{i}^{k} \quad \frac{a(t_{k-1/2})r}{2}u_{i-1}^{k} \quad \tau f(x_{i}, t_{k-1/2})$$
 (10)

where  $r = \tau/h^2$ , 1 i n - 1, k 0.

Equation (10) can be written as the following Matrix form:

$$AU = b \tag{11}$$

where

$$U^t = (u_1^{k-1}u_2^{k-1}\cdots u_{n-2}^{k-1}u_{n-1}^{k-1})$$

### Discussion of the numerical result

In this section, we perform numerical tests for the algorithm described in [1].

**Example 1.** Consider the problem  $u_t - a(t)u_{xx} = f(x, t), 0 < x < 1, t > 0$  with  $u(x, 0) = e^{-x} + e^{x}e^{-x} = e^{-x}$ , 0 < x < 1;  $u(0, t) = 2e^{e^{t}} - 1$  and  $u(1, t) = (e^{-1} + e)e^{e^{t}} - e$ , t > 0, where  $a(t) = e^{t}$  and  $a(t) = e^{t}$  and  $a(t) = e^{t}$ . The exact solution is  $a(t) = e^{t} - e^{t}$ .

The results obtained for u(x, t) are presented in tab. 1.

1 able 1. Result for a with 7 0.20, 11 0.10, 12 0.000, 11 11, and 17 2000										
i	$u_{1,k}$		$u_{5,k}$		$u_{9,k}$					
	Numerical	Exact	Numerical	Exact	Numerical	Exact				
7	4.556774	4.556724	4.704200	4.703988	5.614308	5.613979				
20	4.964895	4.964533	5.161609	5.161554	6.195289	6.195495				
50	6.153402	6.153264	6.497873	6.495325	7.891494	7.890568				
60	6.647447	6.647192	7.052375	7.049517	8.595858	8.594884				
80	7.830298	7.829717	8.376961	8.376323	10.282640	10.281106				
100	9.348352	9.347527	10.084721	10.079323	12.444029	12.445429				

Table 1. Result for u with  $\gamma = 0.98$ , h = 0.1, t = 0.005, k = 11, and N = 5000

**Example 2.** Consider the problem  $u_t - a(t)u_{xx} = f(x, t)$ , 0 < x < 1, t > 0 with  $u(x, 0) = e^x$ , 0 < x < 1;  $u(0, t) = 2e^{e^t}$  1 and  $u(1, t) = e^{t-t^{3/3}}$ , t > 0, where  $a(t) = t^2 + 1$  and  $f(x, t) = xt^2 - x$ . The exact solution is  $u(x, t) = e^{x-t^{3/3}}$  and  $u(x, t) = e^{x-t^{3/3}}$ 

The results obtained for u(x, t) are presented in tab. 2.

i	$u_{1,k}$		$u_{5,k}$		$u_{9,k}$	
	Numerical	Exact	Numerical	Exact	Numerical	Exact
10	1.212557	1.211843	1.772773	1.772893	2.628217	2.629488
20	1.333497	1.333730	1.921650	1.920463	2.832696	2.834588
40	1.646830	1.646405	2.329271	2.323305	3.409811	3.407616
60	2.111359	2.111290	2.964007	2.964443	4.342121	4.341071
80	2.853976	2.854390	4.045561	4.037469	5.927285	5.926223
100	4.127121	4.125985	5.936542	5.921368	8.728614	8.730917

Table 2. Result for u with  $\gamma = 0.98$ , h = 0.1, t = 0.01, k = 15, and N = 2000

#### Conclusion

In this paper, an alternative method is proposed to solve a parabolic problem. We first discretize governing equations by Crank-Nicolson method, and obtain a large sparse system of linear algebraic equations Ax = b, then use Jacobi over-relaxation iterative method and Monte Carlo method to solve the algebraic equations. The numerical results show that the proposed numerical method is accurate to estimate the exact solutions of eq. (1).

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