

CONSTRUCTION OF A VARIATIONAL FORMULATION FOR HEAT TRANSFER

by

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This paper gives two useful methods to construct a variational formulation for heat transfer. Xu's variational principle for heat transfer in terms of entransy is used as an example to elucidate how to correct a wrong variational formulation, and the semi-inverse method is adopted to establish a needed variational principle.

Key words: variational principle, Euler-Lagrange equation, semi-inverse method

Introduction

In 2012, Xu [1] established a variational principle for heat transfer, which is:

$$J(T) = \int_V L dV \quad (1)$$

where L is the entransy defined [1]:

$$L = k \left[\left(\frac{\partial T}{\partial x} \right)^2 + \left(\frac{\partial T}{\partial y} \right)^2 + \left(\frac{\partial T}{\partial z} \right)^2 \right] + kT \left[\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2} \right] \quad (2)$$

The Euler-Lagrange equation of eq. (1) is:

$$\begin{aligned} & \frac{\partial L}{\partial T} - \frac{\partial}{\partial x} \frac{\partial L}{\partial T_x} - \frac{\partial}{\partial y} \frac{\partial L}{\partial T_y} - \frac{\partial}{\partial z} \frac{\partial L}{\partial T_z} - \frac{\partial^2}{\partial x^2} \frac{\partial L}{\partial T_{xx}} \\ & - \frac{\partial^2}{\partial y^2} \frac{\partial L}{\partial T_{yy}} - \frac{\partial^2}{\partial z^2} \frac{\partial L}{\partial T_{zz}} - \frac{\partial^2}{\partial xy} \frac{\partial L}{\partial T_{xy}} - \frac{\partial^2}{\partial xz} \frac{\partial L}{\partial T_{xz}} - \frac{\partial^2}{\partial yz} \frac{\partial L}{\partial T_{yz}} = 0 \quad (3) \end{aligned}$$

where the subscribes imply the partial differentiation, *i. e.* $T_x = \partial T / \partial x$, $T_{xx} = \partial^2 T / \partial x^2$.

By a simple calculation, we have:

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$$k \frac{\partial^2 T}{\partial x^2} - \frac{\partial^2 T}{\partial y^2} - \frac{\partial^2 T}{\partial z^2} - 2k \frac{\partial}{\partial x} \frac{\partial T}{\partial x} - \frac{\partial}{\partial y} \frac{\partial T}{\partial y} - \frac{\partial}{\partial z} \frac{\partial T}{\partial z} - k \frac{\partial^2}{\partial x^2}(T) - \frac{\partial^2}{\partial y^2}(T) - \frac{\partial}{\partial z^2}(T) = 0 \quad (4)$$

Equation (4) implies $0 = 0$. We therefore, conclude that Xu's variational principle is wrong. In this paper we will show how to establish a needed variational formulation for practical applications.

Construction of a variational formulation

Try-and-error method

The Lagrange function given in eq. (2) gives a wrong result, so eq. (2) requires some modification. In this paper, we give the following correction:

$$L = ak \left[\frac{\partial T}{\partial x} \right]^2 + \left[\frac{\partial T}{\partial y} \right]^2 + \left[\frac{\partial T}{\partial z} \right]^2 - bkT \left[\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2} \right] \quad (5)$$

where a and b are constants.

The Euler-Lagrange equation of eq. (5) reads:

$$ak \left[\frac{\partial}{\partial x} \frac{\partial T}{\partial x} + \frac{\partial}{\partial y} \frac{\partial T}{\partial y} + \frac{\partial}{\partial z} \frac{\partial T}{\partial z} \right] - bk \left[\frac{\partial^2}{\partial x^2}(T) + \frac{\partial^2}{\partial y^2}(T) + \frac{\partial^2}{\partial z^2}(T) \right] = 0 \quad (6)$$

or

$$(b - a)k \left[\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2} \right] = 0 \quad (7)$$

It requires that $a = b$.

Semi-inverse method

The semi-inverse method was proposed in 1997 to establish a variational formulation directly from governing equations [2]. Hereby we consider a general heat transfer:

$$\frac{\partial}{\partial x} \left(k_x \frac{\partial T}{\partial x} \right) + \frac{\partial}{\partial y} \left(k_y \frac{\partial T}{\partial y} \right) + \frac{\partial}{\partial z} \left(k_z \frac{\partial T}{\partial z} \right) = Q \quad (8)$$

where k_x , k_y , k_z , and Q are constants or function of co-ordinates.

The semi-inverse method begins with a trial Lagrange function with an energy form. For example:

$$L = k_x \left[\frac{\partial T}{\partial x} \right]^2 - F \quad (9)$$

where F is an unknown function of T and/or its derivatives. Alternative approaches to construction of the Lagrange function was discussed in [3-6].

The Euler-Lagrange equation for eq. (9) is:

$$2 \frac{\partial}{\partial x} k_x \frac{\partial T}{\partial x} - \frac{\delta F}{\delta T} = 0 \quad (10)$$

where $\delta F/\delta T$ is the variational derivative defined:

$$\begin{aligned} \frac{\delta F}{\delta T} = & \frac{\partial}{\partial x} \frac{\partial F}{\partial T_x} + \frac{\partial}{\partial y} \frac{\partial F}{\partial T_y} + \frac{\partial}{\partial z} \frac{\partial F}{\partial T_z} + \frac{\partial^2}{\partial x^2} \frac{\partial F}{\partial T_{xx}} \\ & + \frac{\partial^2}{\partial y^2} \frac{\partial F}{\partial T_{yy}} + \frac{\partial^2}{\partial z^2} \frac{\partial F}{\partial T_{zz}} + \frac{\partial^2}{\partial xy} \frac{\partial F}{\partial T_{xy}} + \frac{\partial^2}{\partial xz} \frac{\partial F}{\partial T_{xz}} + \frac{\partial^2}{\partial yz} \frac{\partial F}{\partial T_{yz}} + \dots \end{aligned} \quad (11)$$

Equation (10) should satisfy eq. (8), this requires that:

$$\frac{\delta F}{\delta T} - 2 \frac{\partial}{\partial x} k_x \frac{\partial T}{\partial x} - 2Q - 2 \frac{\partial}{\partial y} k_y \frac{\partial T}{\partial y} - \frac{\partial}{\partial z} k_z \frac{\partial T}{\partial z} = 0 \quad (12)$$

From eq. (12), F can be identified, which reads:

$$F = k_x \frac{\partial T}{\partial x}^2 + k_y \frac{\partial T}{\partial y}^2 + k_z \frac{\partial T}{\partial z}^2 - 2QT \quad (13)$$

We, therefore, obtain a needed Lagrange function:

$$L = k_x \frac{\partial T}{\partial x}^2 + k_y \frac{\partial T}{\partial y}^2 + k_z \frac{\partial T}{\partial z}^2 - 2QT \quad (14)$$

Remark 1

In case $k_x = k_y = k_z = k$ and $Q = 0$, eq. (14) is equivalent to eq. (5) when $a = 1$ and $b = 0$.

Remark 2

When Q is a function of T , the Lagrange function becomes:

$$L = k_x \frac{\partial T}{\partial x}^2 + k_y \frac{\partial T}{\partial y}^2 + k_z \frac{\partial T}{\partial z}^2 - 2QT \quad (15)$$

where Q is calculated from the equation:

$$Q = \frac{\partial q}{\partial T} \quad (16)$$

Conclusions

This paper shows how to correct a wrong variational formulation by a try-and-error method, and the semi-inverse method is adopted to establish a needed formulation, formulation directly from the governing equations.

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