

THE EXTENDED VARIATIONAL ITERATION METHOD FOR LOCAL FRACTIONAL DIFFERENTIAL EQUATION

by

Yong-Ju YANG*

School of Mathematics and Statistics, Nanyang Normal University, Nanyang, China

Original scientific paper
<https://doi.org/10.2298/TSCI200201054Y>

An extended variational iteration method within the local fractional derivative is introduced for the first time, where two Lagrange multipliers are adopted. Moreover, the sufficient conditions for convergence of the new variational iteration method are also established.

Key words: *variational iteration method, boundary value problems, Lagrange's multiply, local fractional calculus*

Introduction

The development of physical science and engineering has promoted the generation of various incompatible fractional derivatives, and it is an active research field to choose an appropriate fractional calculus according to a real physical problem. For examples, He's fractional derivative [1] was adopted to describe polar hair's thermal property [2], the fractional Caputo-Fabrizio derivative was applied to the groundwater and thermal science [3], the local fractional calculus was used to process silk cocoon hierarchy [4], He's fractal derivative was applied to explanation of snow's thermal insulation property [5], adsorption kinetics [6], biomechanism of polar hairs [7, 8], microgravity fluid [9], convection-diffusion process [10], and two-scale thermodynamics [11-13].

The local fractional calculus was firstly introduced by Yang [14], which could be used as a powerful tool to describing the motion of a fluid in a porous medium, and this calculus currently has a wide range of physical applications, such as [15-20].

The variational iteration method was first proposed by He [21], and the improvements and applications of the variational iterative method have been an active issue in solving differential equations, such as [22-33]. In this paper, we extend the variational iteration method by modifying the correction functional to make it more suitable for solving differential equations.

Local fractional operators

In this section, we introduce two definitions of the local fractional calculus theory, which shall be used in this paper [14].

* Author's e-mail: tomjohn1007@126.com

Definition 1. In fractal space, the local fractional derivative of $f(x)$ of order α at $x = x_0$ is defined:

$$D_x^{(\alpha)} f(x_0) = f^{(\alpha)}(x_0) = \frac{d^\alpha f(x)}{dx^\alpha} \Big|_{x=x_0} = \lim_{x \rightarrow x_0} \frac{\Delta^\alpha [f(x) - f(x_0)]}{(x - x_0)^\alpha} \quad (1)$$

where

$$\Delta^\alpha [f(x) - f(x_0)] \cong \Gamma(1 + \alpha) \Delta [f(x) - f(x_0)]$$

Definition 2. If a function $f(x) \in C[a, b]$, the local fractional integral of $f(x)$ of order α in the interval $[a, b]$ is defined:

$${}_a I_b^{(\alpha)} f(x) = \frac{1}{\Gamma(1 + \alpha)} \int_a^x f(t) (dt)^\alpha = \frac{1}{\Gamma(1 + \alpha)} \lim_{\Delta t \rightarrow 0} \sum_{j=0}^{N-1} f(t_j) (\Delta t_j)^\alpha \quad (2)$$

where

$$\Delta t_j = t_{j+1} - t_j, \Delta t = \max \{ \Delta t_1, \Delta t_2, \Delta t_3, \dots \}$$

and

$$[t_j, t_{j+1}], j = 0, \dots, N-1, t_0 = a, t_N = b$$

is a partition of the interval $[a, b]$.

The extended variational iteration method for local fractional differential equation

Consider the following local fractional differential equation:

$$\frac{d^{2\alpha} u(x)}{dx^{2\alpha}} + k_1 \frac{d^\alpha u(x)}{dx^\alpha} + k_2 u(x) + L[u(x)] + N[u(x)] = f(x), \quad (3)$$

$$u(a) = \beta_1, \quad u(b) = \beta_2$$

where L and N are linear and non-linear operators, respectively, which depict the fractal behaviors of the physical processes, k_1 and k_2 are all real constants, β_1 and β_2 – the initial conditions, and where $f(x)$ is the inhomogeneous part.

Moreover, α is the value of fractal dimensions of the porous medium. For $\alpha = 1$, the proposed medium dose not have holes.

Based on the classic variational iteration method, we modify the classic correction functional for eq. (3):

$$u_{n+1} = u_n + \frac{1}{\Gamma(1 + \alpha)} \int_a^x \lambda_1(t, x) f(t) (dt)^\alpha + \frac{1}{\Gamma(1 + \alpha)} \int_x^b \lambda_2(t, x) f(t) (dt)^\alpha \cdot$$

$$\cdot \frac{1}{\Gamma(1 + \alpha)} \int_a^x \lambda_1(t, x) \left[\frac{d^{2\alpha} u_n}{dt^{2\alpha}} + k_1 \frac{\partial^\alpha u_n}{\partial t^\alpha} + k_2 u_n + L\tilde{u}_n + N\tilde{u}_n \right] (dt)^\alpha +$$

$$+ \frac{1}{\Gamma(1 + \alpha)} \int_x^b \lambda_2(t, x) \left[\frac{\partial^{2\alpha} u_n}{\partial t^{2\alpha}} + k_1 \frac{\partial^\alpha u_n}{\partial t^\alpha} + k_2 u_n + L\tilde{u}_n + N\tilde{u}_n \right] (dt)^\alpha \quad (4)$$

where $\lambda_1(t, x)$ and $\lambda_2(t, x)$ are two general Lagrange's multipliers defined on the intervals $[a, x]$ and $[x, b]$, respectively, which satisfy the corresponding conditions at $x = a$ and $x = b$, respectively, and where the terms $L[\tilde{u}_n(t)]$ and $R[\tilde{u}_n(t)]$ are all considered as restricted local

fractional variation, *i. e.*, $\delta^a L[\tilde{u}_n(t)] = 0$ and $\delta^a R[\tilde{u}_n(t)] = 0$. The selected initial term $u_0(x)$ should satisfy the given boundary conditions of eq. (3).

Next, we will derive the proper correctional functional for eq. (3) and accordingly construct the extended variation iterative scheme:

$$\begin{aligned} u_{n+1}(x) = & u_n(x) + \frac{1}{\Gamma(1+\alpha)} \int_a^x \lambda_1(t, x) f(t) (dt)^\alpha + \frac{1}{\Gamma(1+\alpha)} \int_x^b \lambda_2(t, x) f(t) (dt)^\alpha \cdot \\ & \cdot \frac{1}{\Gamma(1+\alpha)} \int_a^x \lambda_1(t, x) \left[\frac{d^{2\alpha} u_n(t)}{dt^{2\alpha}} + k_1 \frac{d^\alpha u_n(t)}{dt^\alpha} + k_2 u_n(t) + Lu_n(t) + N\tilde{u}_n(t) \right] (dt)^\alpha + \\ & + \frac{1}{\Gamma(1+\alpha)} \int_x^b \lambda_2(t, x) \left[\frac{d^{2\alpha} u_n(t)}{dt^{2\alpha}} + k_1 \frac{d^\alpha u_n(t)}{dt^\alpha} + k_2 u_n(t) + Lu_n(t) + N\tilde{u}_n(t) \right] (dt)^\alpha \end{aligned} \quad (5)$$

where the Lagrange's multipliers $\lambda_1(t, x)$ and $\lambda_2(t, x)$ satisfy the corresponding conditions at $x = a$ and $x = b$, respectively, *i. e.* $\lambda_1(t, x) = 0$ and $\lambda_2(t, x) = 0$.

To find the optimal values of $\lambda_1(t, x)$ and $\lambda_2(t, x)$, we proceed as follows. Integrating by parts within each of the integrals in eq. (5), we have:

$$\begin{aligned} u_{n+1}(x) = & \frac{1}{\Gamma(1+\alpha)} \left[\int_a^x \lambda_1^{(2\alpha)}(t) u_n(t) (dt)^\alpha - k_1 \int_a^x \lambda_1^{(\alpha)}(t) u_n(t) (dt)^\alpha + k_2 \int_a^x \lambda_1 u_n(t) (dt)^\alpha \right] + u_n(x) + \\ & + \lambda_1^{(\alpha)}(x, a) u_n(a) + \lambda_1(x, x) u_n^{(\alpha)}(x) - \lambda_1(x, a) u_n^{(\alpha)}(a) + k_1 \lambda_1(x, x) u_n(x) - k_1 \lambda_1(x, a) u_n(a) - \\ & - \lambda_1^{(\alpha)}(x, x) u_n(x) - \lambda_2(x, x) u_n^{(\alpha)}(x) + \lambda_2(x, b) u_n^{(\alpha)}(b) - k_1 \lambda_2(x, x) u_n(x) + \\ & + k_1 \lambda_2(x, b) u_n(b) + \lambda_2^{(\alpha)}(x, x) u_n(x) - \lambda_2^{(\alpha)}(x, b) u_n(b) - \\ & - \frac{1}{\Gamma(1+\alpha)} \left[\int_x^b \lambda_2^{(2\alpha)}(t) u_n(t) (dt)^\alpha - k_1 \int_x^b \lambda_2^{(\alpha)}(t) u_n(t) (dt)^\alpha + k_2 \int_x^b \lambda_2 u_n(t) (dt)^\alpha \right] \end{aligned} \quad (6)$$

Next, taking the variation with respect to $u_n(x)$ of both sides of eq. (6), we obtain

$$\begin{aligned} \delta u_{n+1}(x) = & \left(1 - \lambda_1^{(\alpha)} + k_1 \lambda_1 + \lambda_2^{(\alpha)} - k_1 \lambda_2 \Big|_{t=x} \right) \delta u_n(x) + \\ & + \frac{1}{\Gamma(1+\alpha)} \delta \left[\int_a^x \lambda_1^{(2\alpha)}(t) u_n(t) (dt)^\alpha - k_1 \int_a^x \lambda_1^{(\alpha)}(t) u_n(t) (dt)^\alpha + k_2 \int_a^x \lambda_1 u_n(t) (dt)^\alpha \right] \cdot \\ & \cdot (\lambda_{12} - \lambda_2 \Big|_{t=x}) \delta u'_n(x) + \frac{1}{\Gamma(1+\alpha)} \delta \left[\int_x^b \lambda_2^{(2\alpha)}(t) u_n(t) (dt)^\alpha - k_1 \int_x^b \lambda_2^{(\alpha)}(t) u_n(t) (dt)^\alpha + k_2 \int_x^b \lambda_2 u_n(t) (dt)^\alpha \right] \end{aligned} \quad (7)$$

Therefore, we obtain the following stationary conditions:

$$\begin{aligned} \lambda_1^{(2\alpha)} - k_1 \lambda_1^{(\alpha)} + k_2 \lambda_1 &= 0 \\ \lambda_2^{(2\alpha)} - k_1 \lambda_2^{(\alpha)} + k_2 \lambda_2 &= 0 \\ 1 - \lambda_1^{(\alpha)} + k_1 \lambda_1 + \lambda_2^{(\alpha)} - k_1 \lambda_2 \Big|_{t=x} &= 0 \\ \lambda_1 - \lambda_2 \Big|_{t=x} &= 0 \\ \lambda_1(t, b) &= 0 \\ \lambda_2(t, a) &= 0 \end{aligned} \quad (8)$$

By virtue of eq. (8), we can rewrite eq. (6) as:

$$\begin{aligned} u_{n+1}(x) = & -\lambda_1(x, a)u_n^{(\alpha)}(a) - k_1\lambda_1(x, a)u_n(a) + \lambda_1^{(\alpha)}(x, a)u_n(a) + \lambda_2(x, b)u_n^{(\alpha)}(b) + \\ & + k_1\lambda_2(x, b)u_n(b) - \lambda_2^{(\alpha)}(x, b)u_n(b) + \frac{1}{\Gamma(1+\alpha)} \int_a^x \lambda_1(t, x)f(t)(dt)^\alpha + \frac{1}{\Gamma(1+\alpha)} \int_x^b \lambda_1(t, x)f(t)(dt)^\alpha + \\ & + \frac{1}{\Gamma(1+\alpha)} \int_a^x \lambda_2(t, x)Nu_n(t)(dt)^\alpha + \frac{1}{\Gamma(1+\alpha)} \int_x^b \lambda_2(t, x)Nu_n(t)(dt)^\alpha \end{aligned} \quad (9)$$

The eq. (9) does provide an effective tool for constructing the following equivalent integral equation of eq. (3):

$$\begin{aligned} u(x) = & -\lambda_1(x, a)u^{(\alpha)}(a) - k_1\lambda_1(x, a)u(a) + \lambda_1^{(\alpha)}(x, a)u(a) + \lambda_2(x, b)u^{(\alpha)}(b) + k_1\lambda_2(x, b)u(b) - \\ & - \lambda_2^{(\alpha)}(x, b)u(b) + \frac{1}{\Gamma(1+\alpha)} \int_a^x \lambda_1(t, x)f(t)(dt)^\alpha + \frac{1}{\Gamma(1+\alpha)} \int_x^b \lambda_2(t, x)f(t)(dt)^\alpha + \\ & + \frac{1}{\Gamma(1+\alpha)} \int_a^x \lambda_1(t, x)[Lu(t) + Nu(t)](dt)^\alpha + \frac{1}{\Gamma(1+\alpha)} \int_x^b \lambda_2(t, x)[Lu(t) + Nu(t)](dt)^\alpha \end{aligned} \quad (10)$$

The solutions $u(x)$ of eq. (3) can be obtained by the following recursive relation:

$$\begin{aligned} v_0(x) = & \lambda_1^{(\alpha)}(x, a)u(a) - \lambda_2^{(\alpha)}(x, b)u(b) \\ v_{n+1}(x) = & v_0(x) + \frac{1}{\Gamma(1+\alpha)} \int_a^x \lambda_1(t, x)f(t)(dt)^\alpha + \frac{1}{\Gamma(1+\alpha)} \int_x^b \lambda_2(t, x)f(t)(dt)^\alpha \cdot \\ & \cdot \frac{1}{\Gamma(1+\alpha)} \int_a^x \lambda_1(t, x)[Lv_n(t) + Nv_n(t)](dt)^\alpha + \frac{1}{\Gamma(1+\alpha)} \int_x^b \lambda_2(t, x)[Lv_n(t) + Nv_n(t)](dt)^\alpha \end{aligned} \quad (11)$$

and

$$u(x) = \lim_{n \rightarrow \infty} v_n(x) \quad (12)$$

Since there are many choices of the Lagrange multiplier based on eq. (8), many corresponding equivalent integral equations of eq. (3) can be derived.

Convergence analysis

The distance function between function $u(x)$ and function $v(x)$ is defined in the following form:

$$d[u(x), v(x)] = \max_{a \leq x \leq b} |u(x) - v(x)|$$

Theorem 1. If the linear and non-linear local fractional operators $L[u(x)]$ and $N[v(x)]$ satisfy the following Lipschitz conditions, respectively:

$$\begin{aligned} d\{L[u(x)], L[v(x)]\} \leq & M_1 d[u(x), v(x)], M_1 > 0, d\{N[u(x)], N[v(x)]\} \leq \\ \leq & M_2 d[u(x), v(x)], M_2 > 0 \end{aligned} \quad (13)$$

where M_1 and M_2 are all positive constants:

$$m = (M_1 + M_2) \frac{2}{\Gamma^2(1+\alpha)} \left(\int_a^x \lambda_1(t, x)(dt)^\alpha + \int_x^b \lambda_2(t, x)(dt)^\alpha \right), \quad 0 < m < 1 \quad (14)$$

then eq. (11) has a unique solution.

Proof. Let $u(x)$ and $\dot{u}(x)$ be two different solutions for eq. (3), then:

$$\begin{aligned} d[u(x), \dot{u}(x)] &\leq \frac{1}{\Gamma^2(1+\alpha)} d \left[\int_a^x \lambda_1(t, x) Lu(t) (dt)^\alpha, \int_a^x \lambda_1(t, x) L\dot{u}(t) (dt)^\alpha \right] + \\ &+ \frac{1}{\Gamma^2(1+\alpha)} d \left[\int_a^x \lambda_1(t, x) Nu(t) (dt)^\alpha, \int_a^x \lambda_1(t, x) N\dot{u}(t) (dt)^\alpha \right] + \\ &+ \frac{1}{\Gamma^2(1+\alpha)} d \left[\int_x^b \lambda_1(t, x) Lu(t) (dt)^\alpha, \int_x^b \lambda_1(t, x) L\dot{u}(t) (dt)^\alpha \right] + \\ &+ \frac{1}{\Gamma^2(1+\alpha)} d \left[\int_x^b \lambda_1(t, x) Nu(t) (dt)^\alpha, \int_x^b \lambda_1(t, x) N\dot{u}(t) (dt)^\alpha \right] \leq \\ &\leq (M_1 + M_2) \frac{1}{\Gamma^2(1+\alpha)} \left(\int_a^x \lambda_1(t, x) (dt)^\alpha + \int_x^b \lambda_2(t, x) (dt)^\alpha \right) d[u(x), \dot{u}(x)] \end{aligned} \quad (15)$$

Now, we get

$$d[u(x), \dot{u}(x)] \leq md[u(x), \dot{u}(x)]$$

Since $0 < m < 1$, then $d[u(x), \dot{u}(x)] \rightarrow 0$ implies $u(x) = \dot{u}(x)$ and this completes the proof.

Theorem 2. If the conditions shown in *Theorem 1* are satisfied, the solution $v_n(x)$ obtained from (11) converges to the exact solution $u(x)$ of eq. (3).

Proof.

$$\begin{aligned} d[v_{n+1}(x), u(x)] &\leq \frac{1}{\Gamma^2(1+\alpha)} d \left[\int_a^x \lambda_1(t, x) Lv_n(t) (dt)^\alpha, \int_a^x \lambda_1(t, x) Lu(t) (dt)^\alpha \right] + \\ &+ \frac{1}{\Gamma^2(1+\alpha)} d \left[\int_a^x \lambda_1(t, x) Nv_n(t) (dt)^\alpha, \int_a^x \lambda_1(t, x) Nu(t) (dt)^\alpha \right] + \\ &+ \frac{1}{\Gamma^2(1+\alpha)} d \left[\int_x^b \lambda_1(t, x) Lv_n(t) (dt)^\alpha, \int_x^b \lambda_1(t, x) Lu(t) (dt)^\alpha \right] + \\ &+ \frac{1}{\Gamma^2(1+\alpha)} d \left[\int_x^b \lambda_1(t, x) Nv_n(t) (dt)^\alpha, \int_x^b \lambda_1(t, x) Nu(t) (dt)^\alpha \right] \leq \\ &\leq \frac{1}{\Gamma^2(1+\alpha)} (M_1 + M_2) \left(\int_a^x \lambda_1(t, x) (dt)^\alpha + \int_x^b \lambda_2(t, x) (dt)^\alpha \right) d[v_n(x), u(x)] \end{aligned} \quad (16)$$

Since $0 < m < 1$, then $d[v_n(x), u(x)] \rightarrow 0$ as $n \rightarrow \infty$. Therefore, $v_n(x) \rightarrow u(x)$ as $n \rightarrow \infty$. This completes the proof.

Applications

In this section, to demonstrate the applicability of this method, we apply it to the following local fractional differential equations.

Case 1:

$$\frac{d^{2\alpha} u}{dx^{2\alpha}} = A, \quad u(0) = 0, \quad u(1) = A \quad (17)$$

Upon eqs. (8) and (17), we construct the following Lagrange's multipliers:

$$\lambda_1 = -xt + x, \quad 0 \leq t < x, \quad \lambda_2 = (1-x)t, \quad x < t \leq 1 \quad (18)$$

Consequently, based on eqs. (11) and (18), the equivalent integral equation of eq. (17) can be established:

$$u(x, y) = u_0(x, y) + \frac{1}{\Gamma(1+\alpha)} \int_0^x (-xt + x) A(dt)^\alpha + \frac{1}{\Gamma(1+\alpha)} \int_x^1 [(1-x)t] A(dt)^\alpha \quad (19)$$

where

$$u_0(x, y) = \lambda_1^{(\alpha)}(x, a)u(a) - \lambda_2^{(\alpha)}(x, b)u(b)$$

The required solution $u(x)$ for eq. (19) and hence for eq. (17) can be obtained from the recurrence relation:

$$\begin{aligned} v_0(x) &= u_0(x) = -Ax \\ v_{n+1}(x) &= u_0(x) + \frac{1}{\Gamma(1+\alpha)} \int_0^x (-xt + x) A(dt)^\alpha + \\ &+ \frac{1}{\Gamma(1+\alpha)} \int_x^1 [(1-x)t] A(dt)^\alpha = -\frac{1}{2}xA + \frac{x^2A}{2} \end{aligned} \quad (20)$$

Thence

$$u(x) = \lim_{n \rightarrow \infty} v_n(x) = -\frac{3}{2}xA + \frac{x^2A}{2} \quad (21)$$

In the following, let $M_2 > 0$, I only prove that the following equation satisfy the conditions of *Theorems 1 and 2*.

Case 2:

$$\frac{d^{2\alpha}u}{dx^{2\alpha}} + u + M_2 \sin_\alpha u = 0, \quad u(0) = \beta_1, u\left(\frac{\pi}{2}\right) = \beta_2 \quad (22)$$

Upon the eqs. (8) and (22), we have the following Lagrange's multipliers:

$$\begin{aligned} \lambda_1 &= \sin_\alpha(t)^\alpha \cos_\alpha(x)^\alpha, \quad a \leq t < x \\ \lambda_2 &= \cos_\alpha(t)^\alpha \sin_\alpha(x)^\alpha, \quad x < t \leq b \end{aligned} \quad (23)$$

Consequently, based on eqs. (11) and (23), the equivalent integral equation of eq. (22) can be established:

$$\begin{aligned} u(x) &= u_0(x) + \\ &+ \frac{M_2}{\Gamma(1+\alpha)} \int_0^x \sin_\alpha(t)^\alpha \cos_\alpha(x)^\alpha \sin_\alpha u(dt)^\alpha + \\ &+ \frac{M_2}{\Gamma(1+\alpha)} \int_x^{\pi/2} \cos_\alpha(t)^\alpha \sin_\alpha(x)^\alpha \sin_\alpha u(dt)^\alpha \end{aligned} \quad (24)$$

where

$$v_0(x) = \lambda_1^{(\alpha)}(x, 0)\beta_1 - \lambda_2^{(\alpha)}\left(x, \frac{\pi}{2}\right)\beta_2 = \cos_\alpha(x)^\alpha \beta_1 + \sin_\alpha(x)^\alpha \beta_2 \quad (25)$$

Obviously:

$$\begin{aligned} & \frac{M_2}{\Gamma^2(1+\alpha)} \left[\int_0^x \sin_\alpha(t)^\alpha \cos_\alpha(x)^\alpha (dt)^\alpha + \int_x^{\pi/2} \cos_\alpha(t)^\alpha \sin_\alpha(x)^\alpha (dt)^\alpha \right] = \\ & = \frac{M_2}{\Gamma^2(1+\alpha)} \left\{ \cos_\alpha(x)^\alpha \left[1 - \cos_\alpha(x)^\alpha \right] + \sin_\alpha(x)^\alpha \left[1 - \sin_\alpha(x)^\alpha \right] \right\} = \\ & = \frac{M_2}{\Gamma^2(1+\alpha)} \left[\cos_\alpha(x)^\alpha + \sin_\alpha(x)^\alpha - 1 \right] = \\ & = \frac{M_2}{\Gamma^2(1+\alpha)} \left[\sqrt{2} \sin_\alpha \left(x + \frac{\pi}{4} \right)^\alpha - 1 \right] \leq \frac{M_2}{\Gamma^2(1+\alpha)} (\sqrt{2} - 1) \end{aligned} \quad (26)$$

Conclusion

In this paper, an extended variational iteration method is introduced and the sufficient conditions for this method to converge are established. Several examples are given to confirm the validity of this method. As this method greatly enriches the content of variational iterative method, I believe that in the near future, more people will pay attention or discuss this method.

Acknowledgment

This work is supported by the Open Fund Project of State Key Laboratory of Hydro-science and Engineering-Tsinghua University (sklhse-2019-B-05) the key scientific research of Institutions of higher learning in Henan Province Project plan (21A110018) and the foundation of the Nanyang Normal University (2020STP015).

References

- [1] He, J. H., A Tutorial Review on Fractal Space time and Fractional Calculus, *International Journal of Theoretical Physics*, 53 (2014), 11, pp. 3698-3718
- [2] Wang, Q. L., et al., Fractal Calculus and its Application Explanation of Biomechanism of Polar Bear Hairs, *Fractals*, 26 (2018), 6, 1850086
- [3] Abdon, A., Dumitru, B., Caputo-Fabrizio Derivative Applied to Groundwater Flow within Confined Aquifer, *Journal of Engineering Mechanics*, 143 (2017), 5, pp. 1-5
- [4] Liu, F. J., et al., Silkworm (Bombyx Mori) Cocoon vs. Wild Cocoon: Multi-Layer Structure and Performance Characterization, *Thermal Science*, 23 (2019), 4, pp. 2135-2142
- [5] Wang, Y., et al., A Fractal Derivative Model for Snow's Thermal Insulation Property, *Thermal Science*, 23 (2019), 4, pp. 2351-2354
- [6] Liu, H. Y., et al., A Fractal Rate Model for Adsorption Kinetics at Solid/Solution Interface, *Thermal Science*, 23 (2019), 4, pp. 2477-2480
- [7] Wang, Q. L., et al., Fractal Calculus and Its Application Explanation of Biomechanism of Polar Hairs (Vol. 26, 1850086, 2018), *Fractals*, 27 (2019), 5, 1992001
- [8] Wang, Q. L., et al., Fractal Calculus and Its Application Explanation of Biomechanism of Polar Hairs (Vol. 26, 1850086, 2018), *Fractals*, 26 (2018), 6, 1850086
- [9] He, J. H., A Fractal Variational Theory for 1-D Compressible Flow in a Microgravity Space, *Fractals*, 28 (2020), 2, 2050024
- [10] He, J. H., A Simple Approach to 1-D Convection-Diffusion Equation and Its Fractional Modification for E Reaction Arising in Rotating Disk Electrodes, *Journal of Electroanalytical Chemistry*, 854 (2019), 113565
- [11] He, J. H., Ain, Q. T., New Promises and Future Challenges of Fractal Calculus: from Two-Scale Thermodynamics to Fractal Variational Principle, *Thermal Science*, 24 (2020), 2A, pp. 659-681
- [12] Ain, Q. T., He, J. H., On Two-Scale Dimension and Its Application, *Thermal Science*, 23 (2019), 3B, pp. 1707-1712

- [13] He, J. H., Ji, F. Y., Two-Scale Mathematics and Fractional Calculus for Thermodynamics, *Thermal Science*, 23 (2019), 4, pp. 2131-2133
- [14] Yang, X. J., *Advanced Local Fractional Calculus and Its Applications*, World Science Publisher, New York, USA, 2012
- [15] Yang, X. J., Baleanu, D., Fractal Heat Conduction Problem Solved by Local Fractional Variation Iteration Method, *Thermal Science*, 17 (2013), 2, pp. 625-628
- [16] He, J. H., A Short Remark on Fractional Variational Iteration Method, *Phys. Lett. A*, 375 (2011), 38, pp. 3362-3364
- [17] Yang, Y. J., et al., A Local Fractional Variational Iteration Method for Laplace Equation within Local Fractional Operators, *Abstract and Applied Analysis*, 2013 (2013), ID202650
- [18] Yang, Y. J., The Fractional Residual Method for Solving the Local Fractional Differential Equations, *Thermal Science*, 24 (2020), 4, pp. 2535-2542
- [19] Yang, Y. J., The Local Fractional Variational Iteration Method a Promising Technology for Fractional Calculus, *Thermal Science*, 24 (2020), 4, pp. 2605-2614
- [20] Yang, Y. J., Wang, S.-Q., An Improved Homotopy Perturbation Method for Solving Local Fractional Non-Linear Oscillators, *Journal of Low Frequency Noise Vibration and Active Control*, 38 (2019), 3-4, pp. 918-927
- [21] He, J. H., Approximate Analytical Solution for Seepage Flow with Fractional Derivatives in Porous Media, *Comput. Meth Appl. Mech. Eng.*, 167 (1998), 1-2, pp. 57-68
- [22] Wu, G.-C., Lee, E. W. M., Fractional Variational Iteration Method and its Application, *Phys. Lett. A*, 374 (2010), 25, pp. 2506-2509
- [23] Wu, G. C., Baleanu, D., Variational Iteration Method for the Burgers' flow with Fractional Derivatives – New Lagrange Multipliers, *Appl. Math. Model.*, 37 (2013), 9, pp. 6183-6190
- [24] Goswami, P., Solutions of Fractional Differential Equations by Sumudu Transform and Variational Iteration Method, *Journal of Non-Linear Science and Applications*, 9 (2016), 4, pp. 1944-1951
- [25] Yang, Y. J., A New Method Solving Local Fractional Differential Equations in Heat Transfer, *Thermal Science*, 23 (2019), 3A, pp. 1663-1669
- [26] Tao, Z. L., et al., Variational Iteration Method with Matrix Lagrange Multiplier for Non-Linear Oscillators, *Journal of Low Frequency Noise Vibration and Active Control*, 38 (2019), 3-4, pp. 984-991
- [27] Ahmad, H., et al., Variational Iteration Algorithm-I with an Auxiliary Parameter for Wave-Like Vibration Equations, *Journal of Low Frequency Noise Vibration and Active Control*, 38 (2019), 3-4, pp. 1113-1124
- [28] He, W., et al., Modified Variational Iteration Method for Analytical Solutions of Non-Linear Oscillators, *Journal of Low Frequency Noise Vibration and Active Control*, 38 (2019), 3-4, pp. 1178-1183
- [29] He, J. H., Latifizadeh, H., A General Numerical Algorithm for Non-Linear Differential Equations by the Variational Iteration Method, *International Journal of Numerical Methods for Heat and Fluid-Flow*, 30 (2020), 11, pp. 4797-4810
- [30] Anjum, N., He, J. H., Laplace Transform: Making the Variational Iteration Method Easier, *Applied Mathematics Letters*, 92 (2019), June, pp. 134-138
- [31] He, J. H., Jin, X., A Short Review on Analytical Methods for the Capillary Oscillator in a Nanoscale Deformable Tube, *Mathematical Methods in the Applied Sciences*, On-line first, <https://doi.org/10.1002/mma.6321>, 2020
- [32] He, J. H., The Simpler, the Better: Analytical Methods for Non-Linear Oscillators and Fractional Oscillators, *Journal of Low Frequency Noise Vibration and Active Control*, 38 (2019), 3-4, pp. 1252-1260
- [33] He, J. H., A Short Review on Analytical Methods for a Fully Fourth Order Non-Linear Integral Boundary Value Problem with Fractal Derivatives, *International Journal of Numerical Methods for Heat and Fluid-Flow*, 30 (2020), 11, pp. 4937-4943