NUMERICAL SIMULATION OF SUDDEN-EXPANSION
PARTICLE-LADEN FLOWS USING
THE EULERIAN-LAGRANGIAN APPROACH

by

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A Lagrangian-Eulerian model for the dispersion of solid particles in sudden-expansion flows is reported and validated. The fluid was calculated based on the Eulerian approach by solving the Navier-Stokes equations. A Lagrangian model is also applied, using a Runge-Kutta method to obtain the particle trajectories. The effect of fluid turbulence upon particle dispersion is taken into consideration through a statistical model. The predicted axial mean velocity and turbulent kinetic energy of both phases agree well with experimental data reported by Sommerfield.

Key words: Eulerian-Lagrangian model, gas-particles, sudden-expansion

Introduction

Two-phase flows can be found in several industrial processes involving e.g. transport conveying, separation of solid particles, and pulverized-coal combustion.

Nowadays, two categorical approaches for predicting two-phase flows are Eulerian and Lagrangian. In the Eulerian approach two phases are considered to be separate interpenetrating continua, and separate equations of motion are solved for each phase. Recent models of this type are those of Elghobashi [1], Lun [2], and Simonin [3]. This method may be preferably used for dense two-phase flows, for example, in fluidized beds or two-phase flows with phase transition, e.g. from bubbly flow to mist flow. In the Lagrangian approach the dispersed phase is treated by solving Lagrangian equations for the trajectories of a statistically significant sample of individual particles, while the liquid phase is treated as a continuum in the Eulerian approach. The two-way coupling between both phases is also accounted, Berlemeont et al. [4, 5], Lain et al. [6, 7]. The Eulerian-Lagrangian approach allows an easy implementation of physical effects occurring on the scale of the particle size as, for example, particle-particle interactions and particle-wall collisions. The key element of the Eulerian-Lagrangian approach is how it takes account of the effects of turbulent fluctuations on particle, as well as the effects of particles on turbulence properties of the liquid phase.

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Historically, turbulent two-phase free jets have been the subject of many studies but, until very recently it has been difficult to find in the literature a well-documented numerical study of a two-phase turbulent sudden expansion jet. For an improved understanding of the characteristics of sudden expansion particle-laden flows are necessary.

A Eulerian-Lagrangian model was used to solve the governing equations of particle and liquid phase. The Eulerian framework was used for the liquid phase, whereas the Lagrangian approach was used for the particle phase. The steady-state equations of conservation of mass and momentum were used for the liquid phase, and the effect of turbulence on the flow-field was included via the standard \( k-e \) model. The particle equation of motion included the drag force. Turbulence dispersion effect on the particles was simulated by statistical model. The effects of particles on the flow were modelled by appropriate source terms in the momentum equation.

This paper is organized as follows. In next section, the mathematical model is discussed. In the section Numerical procedure and boundary conditions, the numerical procedure and boundary conditions are presented. Finally, the numerical results which the predicted axial mean velocity and turbulent kinetic energy of both phases are compared with experimental data of Sommerfield [8].

Mathematical model

This section describes the mathematical model for turbulent liquid-particle flows assuming that the particulate phase is diluted, so that inter-particle effects are neglected. It is also assumed that the mean flow is steady and the material properties of the phases are constant.

The liquid phase has been calculated based on the Euler approach. The particle phase was treated following the Lagrangian approach, which means that the parameters of every particle are functions of time. For the coupling of phases, the PSI-CELL method of Crowe et al. [9] was chosen. By this method all influences of the dispersed phases on the continuous phase are accounted for through source terms in momentum equation.

Gas-phase flow model

The motion of the fluid is described by the continuity and the Navier-Stokes equations. Turbulence is modelled by the standard model Patanakar [10]. According to the experiment, the sudden-expansion particle-laden flows are considered to be steady axisymmetrical turbulent liquid-particle flows, with these assumptions, the corresponding governing equations for the liquid phase then are:

- **continuity**

  \[
  \frac{\partial (\rho U_i)}{\partial x_j} = 0
  \]

- **Navier-Stokes**

  \[
  \frac{\partial}{\partial x_j} \left[ \rho U_i U_j - \mu \frac{\partial U_i}{\partial x_j} \right] = - \frac{\partial P}{\partial x_i} - \frac{\partial (\rho u_i u_j)}{\partial x_j} + S_{u_i}^p
  \]

In these equations \( U_i \) denotes the Cartesian velocity components, \( P \) – the fluid pressure, and \( \rho \) and \( \mu \) are the density and viscosity of the fluid, respectively.
The turbulence was represented here by the \( k-e \) model, which implies the need to solve two additional equations, namely:

- **turbulent kinetic energy**

\[
\frac{\partial}{\partial x_j} \left[ \rho U_j \frac{\mu_{\text{eff}}}{\sigma_k} \frac{\partial k}{\partial x_j} \right] = P_k - \rho \varepsilon \quad (3)
\]

- **turbulent dissipation**

\[
\frac{\partial}{\partial x_j} \left[ \rho U_j \frac{\mu_{\text{eff}}}{\sigma_\varepsilon} \frac{\partial \varepsilon}{\partial x_j} \right] = \frac{\varepsilon}{k} \left( C_1 P_k - C_2 \rho \varepsilon \right) \quad (4)
\]

where \( \mu_i \) is the turbulent viscosity given by \( \mu_i = C_{\mu} \rho k^2/\varepsilon \).

For the \( k-e \) model, the following standard coefficients are used, tab. 1.

The interaction between particles and the liquid phase yields source terms in the governing equation for conservation of momentum is considered. The standard expression for the momentum equation source terms due to the particles has been used. It is obtained by time and ensemble averaging for each control volume in the form:

\[
S_{\text{V}} = \frac{1}{V_{cv}} \sum m_i \left( u_i^{\text{out}} - u_i^{\text{in}} \right) - g \left( 1 - \frac{\rho}{\rho_p} \right) \Delta t \quad (5)
\]

Here \( V_{cv} \) is the control volume, \( m \) – the mass of an individual particle, and \( n \) – the number of real particles.

### Particle equation of motion

The equation of particle motion than can be written as follows:

\[
m_p \frac{du_{p,i}}{dt} = \frac{3 \rho C_D m_p}{4 D_p \rho_p} (u_i - u_{p,i}) + m_p g \left( 1 - \frac{\rho}{\rho_p} \right)
\]

\[
\frac{dx_{p,i}}{dt} = u_{p,i} \quad (6)
\]

Here \( x_{p,i} \) are the co-ordinates of the particle position, \( u_{p,i} \) – the velocity components, \( D_p \) is the particle diameter and \( \rho_p \) – the particle density.

The term on the right-hand side of eq. (6) is the drag force. Drag force is always present and is generally the dominating force for particle motion in most regions of the flow. Here \( C_D \) is the drag coefficient, which varies with particle Reynolds number, the drag coefficient for the solid particles is given as:

\[
C_D = \begin{cases} 
\frac{24}{Re_p} & (1 + 0.15 Re_p^{0.687}) \quad \text{Re}_p \leq 1000 \\
0.44 & \text{Re}_p > 1000 
\end{cases} \quad (8)
\]

The particle Reynolds number is defined as:
The effect of turbulence on the particle motion is modelled in the present work by a statistical model. The instantaneous liquid velocity along the particle trajectory is sampled from a Gaussian velocity distribution, with the equal RMS value
\[ u' = v' = \frac{2}{3}k \]
in all two Cartesian co-ordinate directions to simulate isotropic turbulence. The instantaneous fluid velocity is assumed to influence the particle motion during a given time period, called the interaction time, before a new fluctuation component is sampled from the Gaussian distribution function.

In the present model, the simulation of the interaction time of a particle with the individual turbulent eddies is limited by the lifetime of the turbulent eddy, \(T_e\), or the transit time, \(T_r\), for the particle to traverse the eddy, i.e.

\[ \Delta_t = \min(T_e, T_r) \]  

where \(T_e = 0.2k/\epsilon\) and the eddy length scale \(l_e = C_{m0}^{0.75}k^{1.5}/\epsilon\). The transit time \(T_r\) can be determined from the linearized form of the particle momentum equation, given by Gosman et al. [11]:

\[ T_r = -\tau_p \ln \left(1 - \frac{l_e}{\tau_p |u_l - u_{p,l}|} \right) \]

where \(\tau_p\) is the particle relaxation time, defined as:

\[ \tau_p = \frac{4}{3} \frac{\rho \epsilon D_p}{\rho C_T |u_l - u_{p,l}|} \]

The Lagrangian approach can follow only a moderate number of particles. The real number of particles in the flow domain, however, is very large. For this reason, the special term parcel of particles was defined. Parcels represent a large bulk of particles with the same size, mass, velocity and position. The model is arranged such that every parcel represents the same mass of a disperse phase.

**Numerical procedure and boundary conditions**

The boundary conditions and flow parameter of the liquid phase and particle phase, as well as for velocity and turbulent kinetic energy at the inlet are given in tab. 2 and tab. 3. Particles are introduced into the flow at 25 different inlet positions between \(r = 0\) m and \(r = 12.75 \times 10^{-3}\) m. The resulting set of equations is solved by using a finite volume discretisation scheme and applying an iterative solution procedure based on the SIMPLE algorithm. This code was extended by introducing the additional source terms to account for the presence of particles.

A solution for the liquid field assuming no particles is initially obtained, and the prediction of the particle motion is carried out. Therefore eqs. (6) and (7) are solved by using a

<table>
<thead>
<tr>
<th>Table 2. Flow parameters</th>
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<tr>
<td><strong>Liquid phase</strong></td>
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<tr>
<td>Density (\rho = 830) kg/m³</td>
</tr>
<tr>
<td>Kinetic viscosity (\nu = 5.205) cst</td>
</tr>
<tr>
<td>Inlet velocity (U_{in} = 6.021) m/s</td>
</tr>
<tr>
<td>Mass flux (f = 2.29) kg/s</td>
</tr>
</tbody>
</table>

* 1 cst = 10⁻² m²/s
standard 4th order Runge-Kutta scheme. The source terms are predicted simultaneously during trajectory calculation. The liquid field is then re-computed with the contribution of particle source terms. The detail of numerical scheme sees Mergheni et al. [12, 13].

Results and discussion

In this section, this simulations result for liquid and particle velocities and turbulence kinetic energy are presented. This simulations were performed for a 2-D downward fully developed sudden-expansion, which is D1 = 25.5·10^{-2} m diameter, D2 = 51·10^{-3} m diameter large and 1.0 m long, fig. 1. In order to obtain a better definition and, possibly a deeper physical understanding of the flow field of a sudden-expansion jet configuration, the radial profiles at various axial stations (x = 9, 50, 100, 150, 200, and 300 mm) are presented one at the inlet of the sudden expansion geometry, three within the recirculation zone and two in the re-development zone.

Figures 2(a) and 3(a) show the presence of recalculating flow regions in the first two calculation sections for both phases. Comparing the experimental and numerical results at x = 9 mm of the mean velocities of fluid and particle, it can be observed the mean velocities are not well predicted. But figs. 2(b) and 3(b) show that the simulated mean particle and fluid velocities are in favourable agreement with the experimental data.

For the turbulent kinetic energy of both phases is shown in figs. 4 and 5. For the near exit region figs. 4(a) and 5(a) the turbulent kinetic increase radially towards the shear layer at r =
= 0.125·10⁻³ m, whereas the other stations (x = 100, 150, and 200 mm) in the centre of the initial region the gas turbulence increases with increasing distances to the nozzle for the fluid and particles. The reason for increased turbulence is high radial diffusive turbulence from the shear layer into the centre of the flow.

In general, the numerical predictions of both phases are in good agreement with Sommerfield [8] measurements especially for axial mean velocities of both phases. The differ-

Figure 3. Axial mean velocity of the particle phase

Figure 4. Turbulent kinetic energy of the liquid phase

Figure 5. Turbulent kinetic energy of the particle phase
ence between the measurement and prediction of radial velocity is caused by the turbulent model of liquid phase. Also, the small magnitude of the radial velocity in the experimental results may carry some error. There could be two reasons for the difference between measurements and prediction of turbulent kinetic energy of both phases. One is due to the assumed inlet conditions, as there are no experimental data available. The other is due to the prediction ability of the $k$-$\varepsilon$ model for liquid phase in sudden expansion flow. Figures 4 and 5 show that, despite these two factors, numerical results of turbulent kinetic energy of both phases are in good agreement with measurements in the downstream region where the effect of the inlet conditions become weak and the $k$-$\varepsilon$ is suitable for a channel flow.

**Conclusion**

Using the Eulerian-Lagrangian model, predicted results of velocity and turbulent kinetic energy of fluid and solid particles of sudden-expansion in a downward fully developed channel flow is represented. A Eulerian-Lagrangian model was used to solve the coupled governing equations of particle-laden flows. The steady-state equations of conservation of mass and momentum were used for the fluid, and the effect of turbulence on the flow-field was included via the standard $k$-$\varepsilon$ model. The particle equation of motion included the drag force. Turbulence dispersion effect on the particles was simulated as a continuous Gaussian random field. The effect of particles on the fluid was considered by inclusion of appropriate source terms in the momentum equation. The predicted axial mean velocity and turbulent kinetic energy of both phases agree well with experimental of Sommerfield [8]. It is concluded that the Eulerian-Lagrangian model has been successfully applied in predicting sudden-expansion particles-laden flows.

**Nomenclature**

- $C_p$, $C_1$, $C_2$: coefficients of the turbulence model
- $C_D$: drag coefficient
- $D$: center jet diameter, [mm]
- $D_p$: particle diameter, [µm]
- $g$: acceleration due to gravity, [ms$^{-1}$]
- $i_e$: eddy size, [m]
- $m_p$: particle mass
- $r$: radial co-ordinate, [m]
- $Re_p$: particle Reynolds number
- $S$: source term
- $T_r$: residence time of the particle, [s]
- $T_e$: turbulent eddy lifetime, [s]
- $\Delta t$: interaction time of particle, [s]
- $u$: axial mean velocity, [ms$^{-1}$]
- $x$: axial co-ordinate, [m]
- $V$: control volume, [m$^3$]

**Greek symbols**

- $\varepsilon$: kinetic energy dissipation rate, [m$^2$s$^{-3}$]
- $\kappa$: kinetic energy of turbulence, [m$^2$s$^{-2}$]
- $\mu$: dynamic viscosity, [kgm$^{-1}$s$^{-1}$]
- $\rho$: gas density, [kgm$^{-3}$]
- $\rho_p$: particle density, [kgm$^{-3}$]
- $r_p$: particle time, [s]
- $\Phi$: particle-loading ratio

**References**


[8] Sommerfeld, M., Particle Dispersion in a Plane Shear Layer, 6th Workshop on Two-Phase Flow Predictions, Erlangen, Germany, 1992


